



# **ATLAS**

## **Principle to Product**

SUPERGEN

26<sup>th</sup> May 2016



*Wind and tidal energy control experts*

# SgurrControl

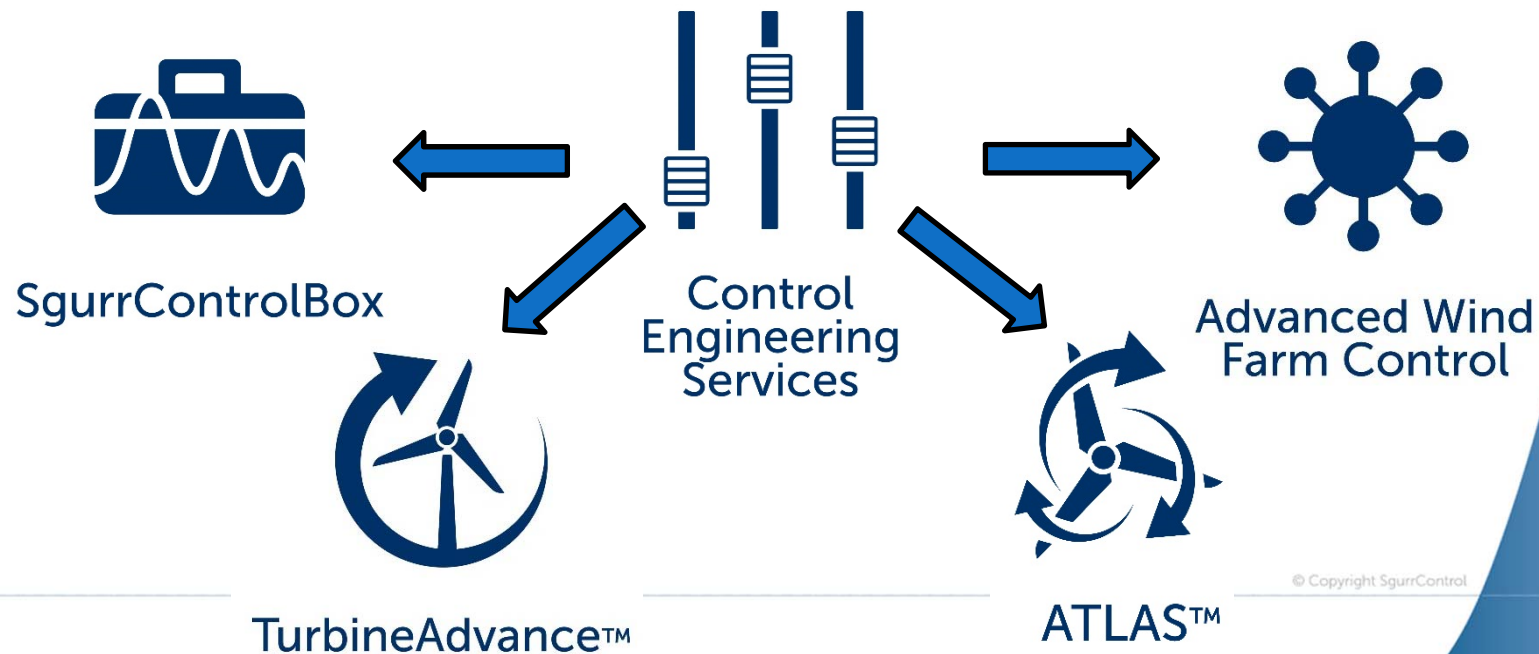
*Experts in wind and tidal energy control*



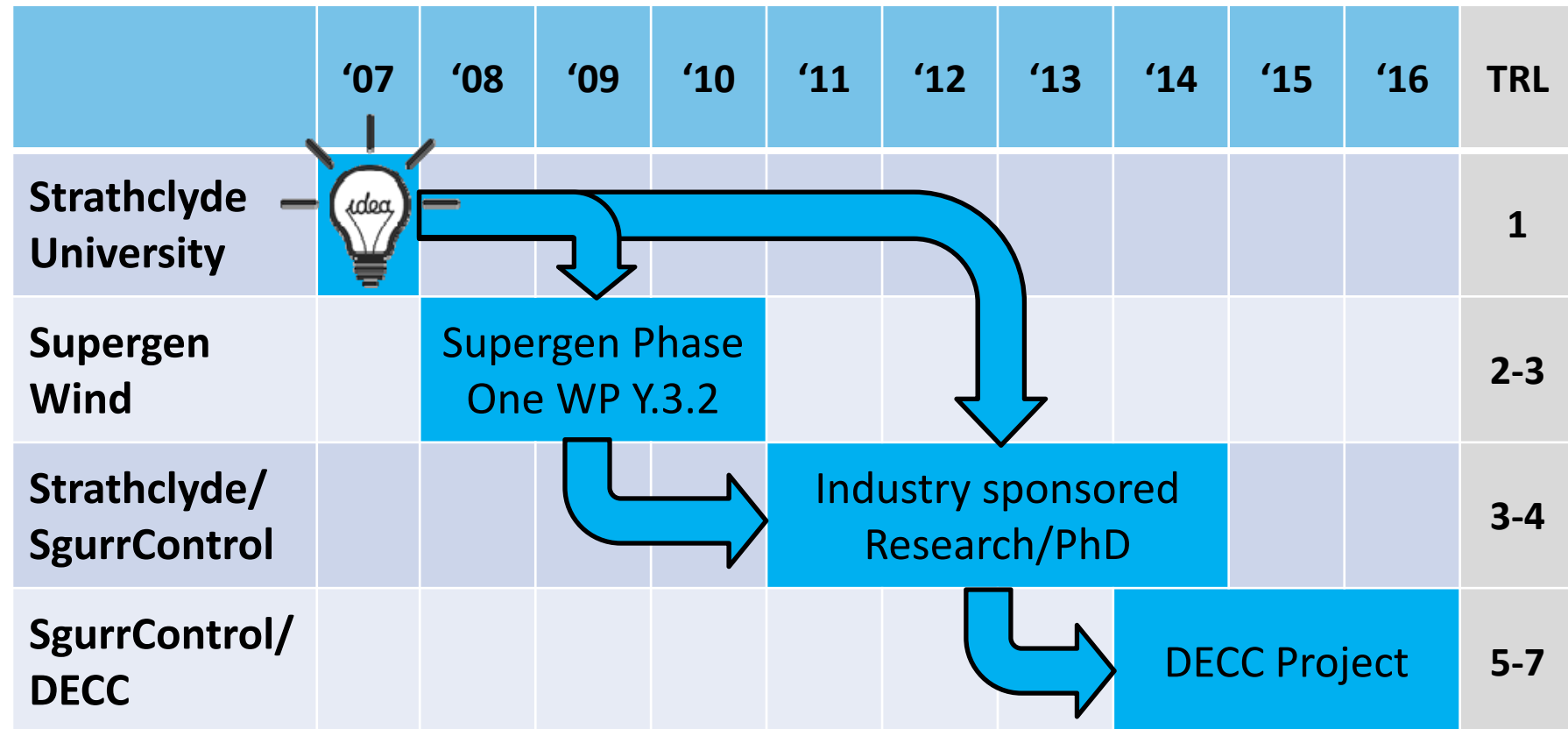
Engineering organisation providing **control solutions** to wind and tidal turbines to:

- Optimise energy capture
- Reduce damage on wind turbines
- Minimise O&M costs

Founded in 2008, joined SgurrEnergy in 2013



# Principle to Product



IBC

Individual Blade Control

ATLAS

Advanced Turbine  
Load Alleviation System



Endpoints of diameter:  $(3,5)$  and  $(-1,-4)$ .

$$\left(\frac{x_1+x_2}{2}, \frac{y_1+y_2}{2}\right) \quad d = \sqrt{(x_2-x_1)^2 + (y_2-y_1)^2}$$

$$\left(\frac{3+(-1)}{2}, \frac{5+(-4)}{2}\right) \quad d = \sqrt{(5-(-1))^2 + (5-(-4))^2}$$

$$\left(1, \frac{1}{2}\right) \quad = \sqrt{4^2 + 9^2}$$

$$(x, y) \quad d = \sqrt{16+81}$$

$$(x, y) \quad d = \sqrt{97} \Rightarrow r = \frac{\sqrt{97}}{2}$$

$$(x-h)^2 + (y-k)^2 = r^2$$

$$(x-1)^2 + \left(y-\frac{1}{2}\right)^2 = \left(\frac{\sqrt{97}}{2}\right)^2$$

$$\therefore (x-1)^2 + \left(y-\frac{1}{2}\right)^2 = \frac{97}{4}$$



Idea

Development

Implementation

Demonstration





Endpoints of diameter  $(3,5)$  and  $(-1,-4)$

$$\left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2} \right) \quad d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

$$\left( \frac{3 + (-1)}{2}, \frac{5 + (-4)}{2} \right) \quad d = \sqrt{(3 - (-1))^2 + (5 - (-4))^2}$$

$$\left( 1, \frac{1}{2} \right) \quad d = \sqrt{4^2 + 9^2}$$

$$(1, \frac{1}{2}) \quad d = \sqrt{16 + 81} \Rightarrow d = \sqrt{97}$$

$$(2-h)^2 + (y-k)^2 = r^2$$

$$(x-1)^2 + (y-\frac{1}{2})^2 = \left(\frac{\sqrt{97}}{2}\right)^2$$

$$(x-1)^2 + (y-\frac{1}{2})^2 = \frac{97}{4}$$



Idea

Development

Implementation

Demonstration

# Control Overview

## Supervisory Control







- 📈 Oversees total operation of wind turbine including
  - 📈 Start-up/shutdown
  - 📈 Safety of turbine operation
  - 📈 Fault handling
  - 📈 Data collection

## Operational Control

- 📈 Continuously adjusts dynamic state of wind turbine
  - 📈 Pitch, generator reaction torque and yaw



# Operational Control

-  Alters the pitch and generator torque demand to control the speed of the rotor
-  Control is used to limit the power output above rated power and optimise power extraction below rated power
-  Control is increasingly used to manage loads on the turbine
  -  Drivetrain load alleviation
  -  Tower load alleviation
  -  Blade loads and rotor imbalance

# Importance of Control on Load Alleviation

## ⌚ Increase in turbine size

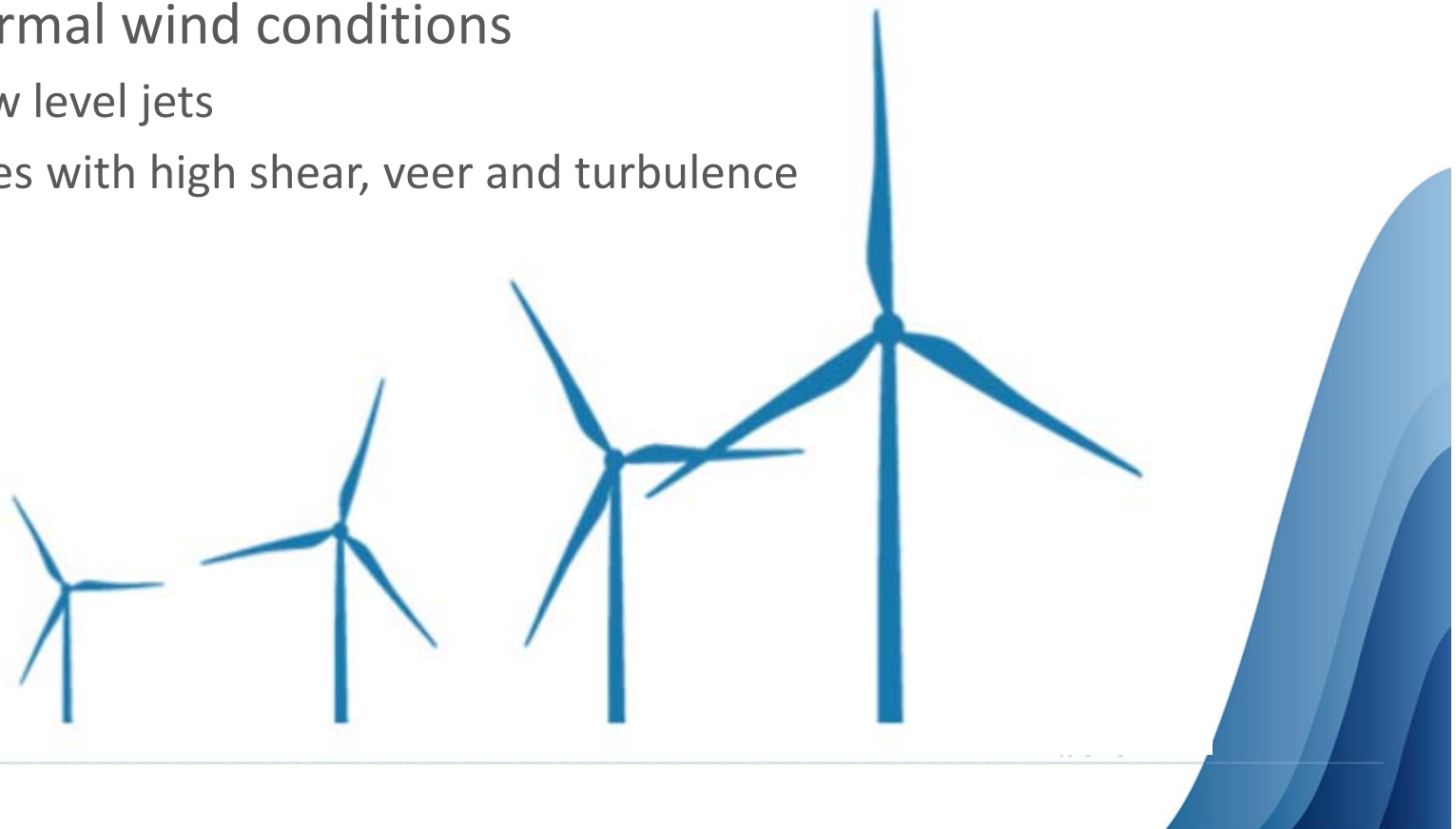
⌚ Square-cube law between energy capture and material requirements

⌚ Size of wind field incident on the rotor

## ⌚ Abnormal wind conditions

⌚ Low level jets

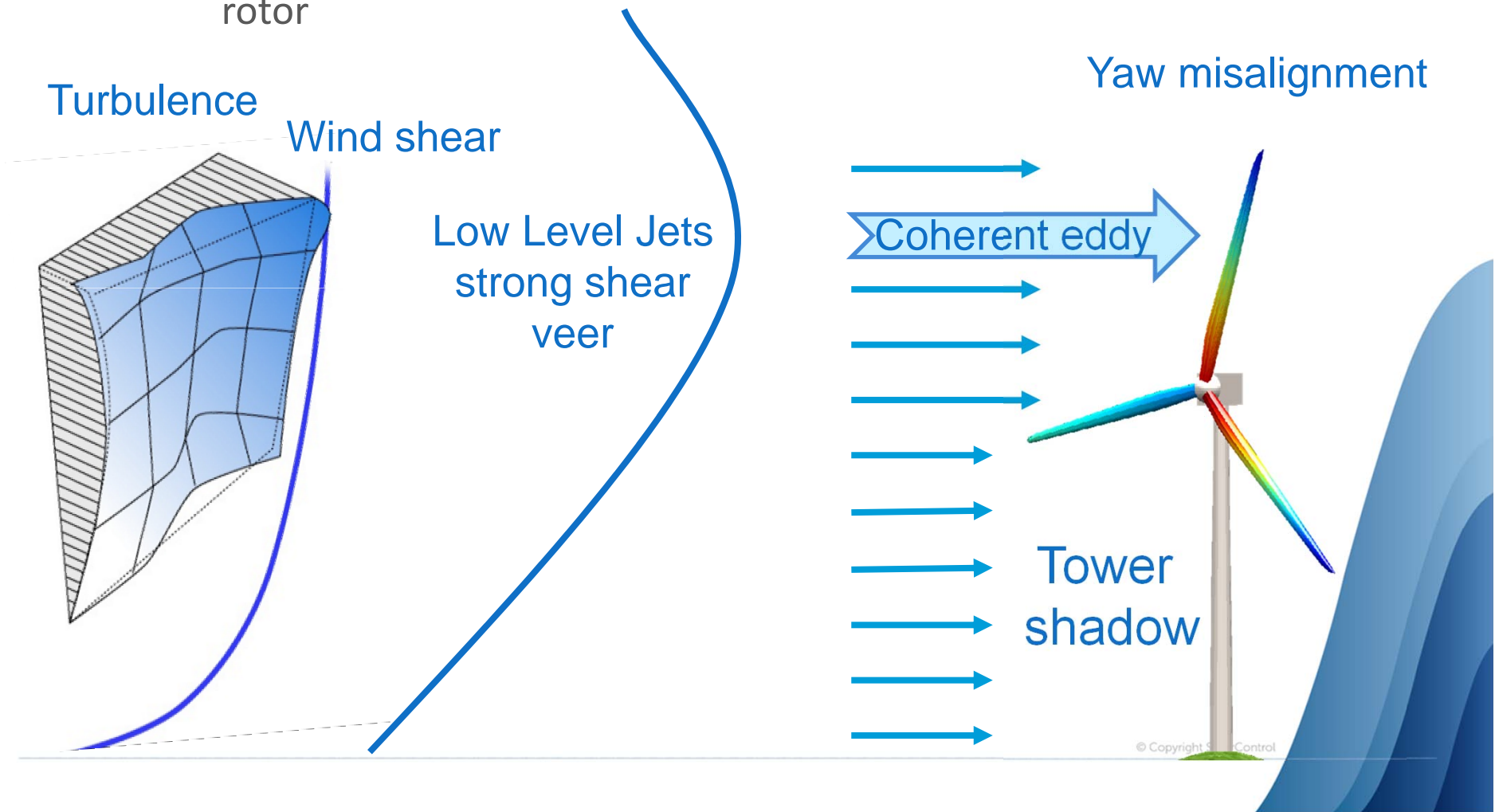
⌚ Sites with high shear, veer and turbulence



# Underlying Cause of Loads

Non-uniform wind fields damaging the turbine

Particularly at the harmonics of the rotational frequency of the rotor





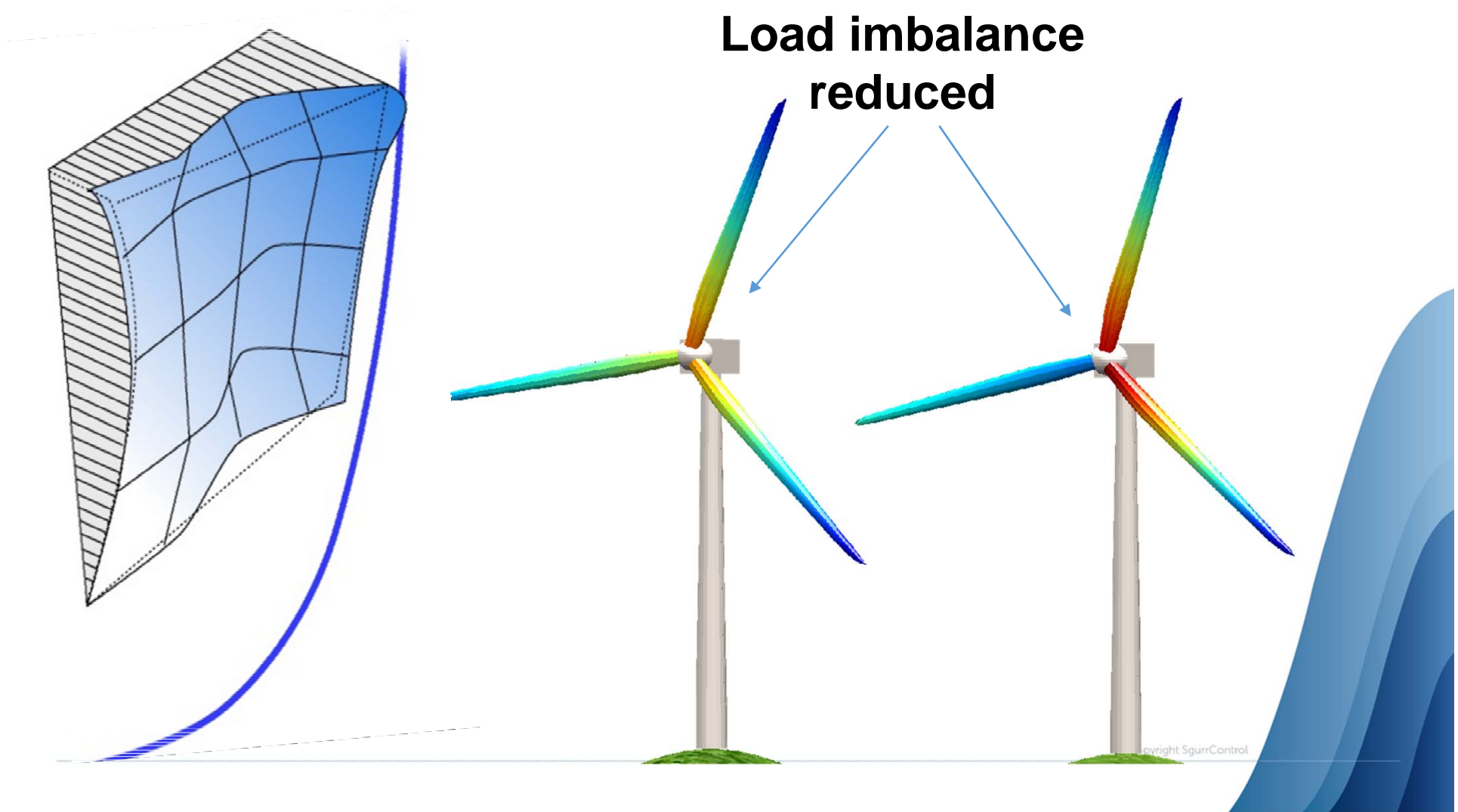
# The Solution

**Collective Pitch  
Control**

**Individual Blade  
Control**


**Wind field**

**Load imbalance  
reduced**



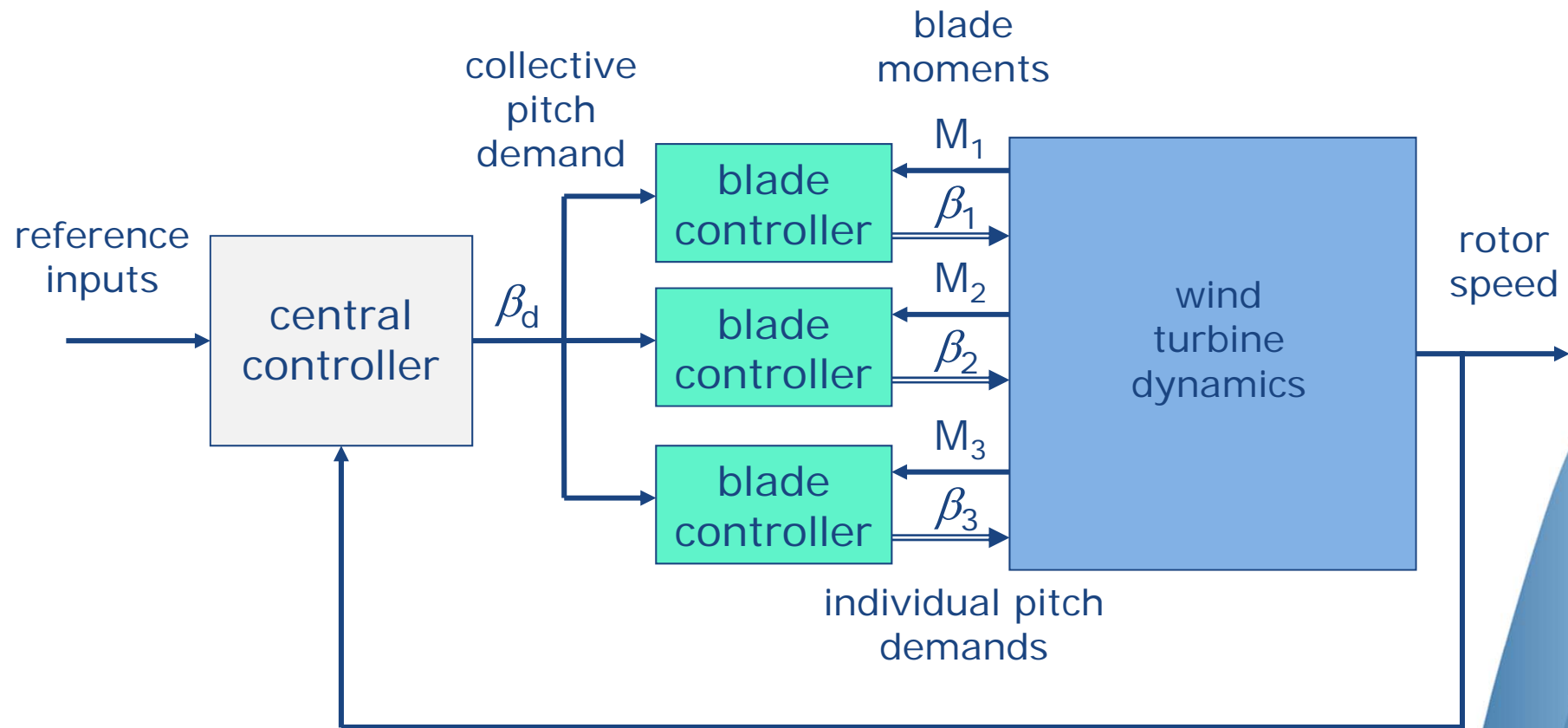
# SUPERGEN Funding



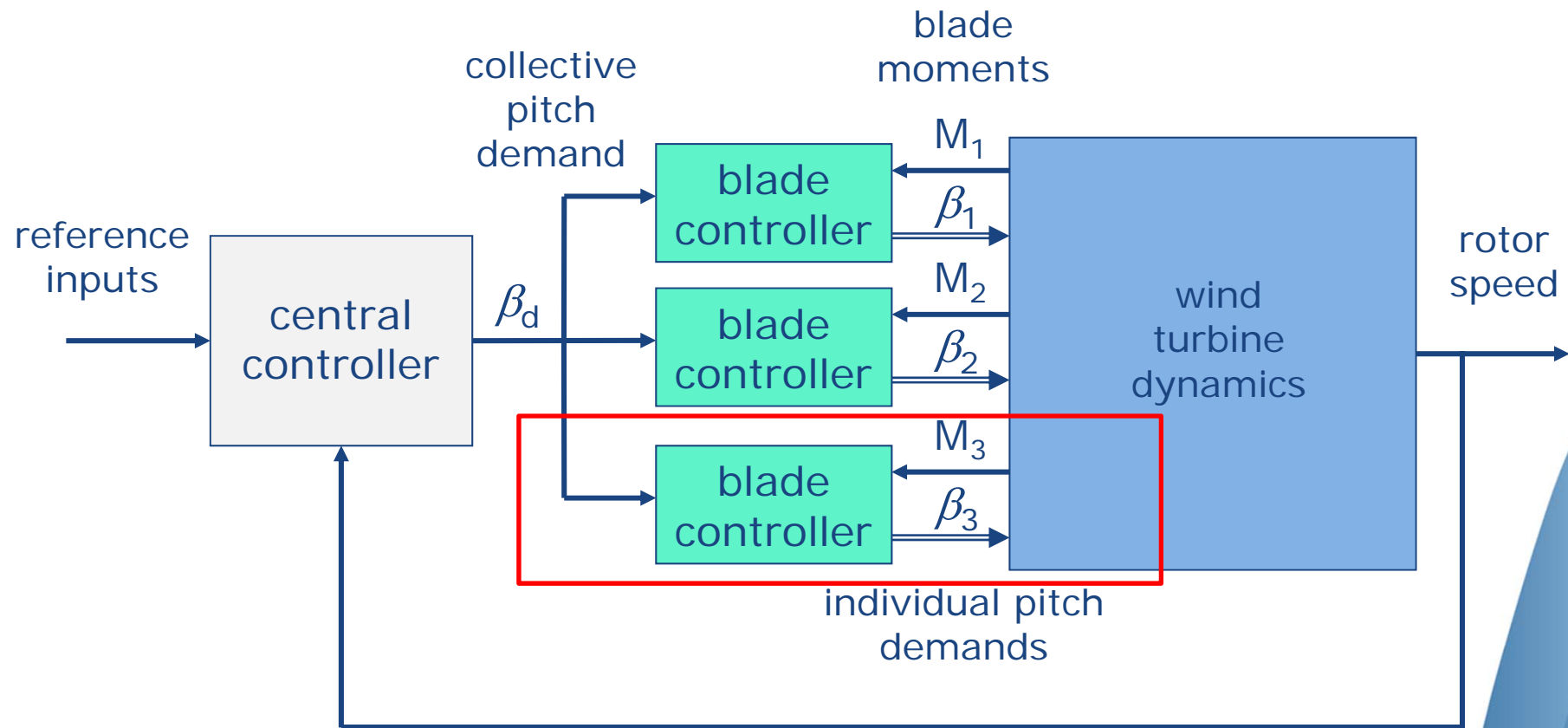
 Individual Blade Control for Fatigue Load Reduction of Large-scaled Wind Turbines: Theory and Modelling (2010),  
Victoria Neilson



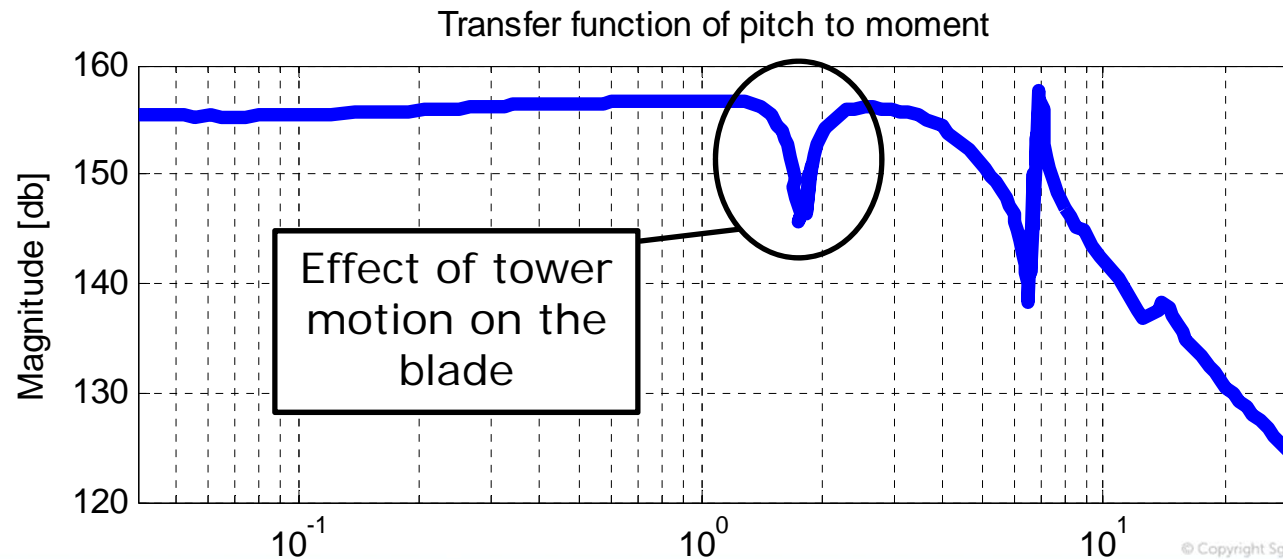
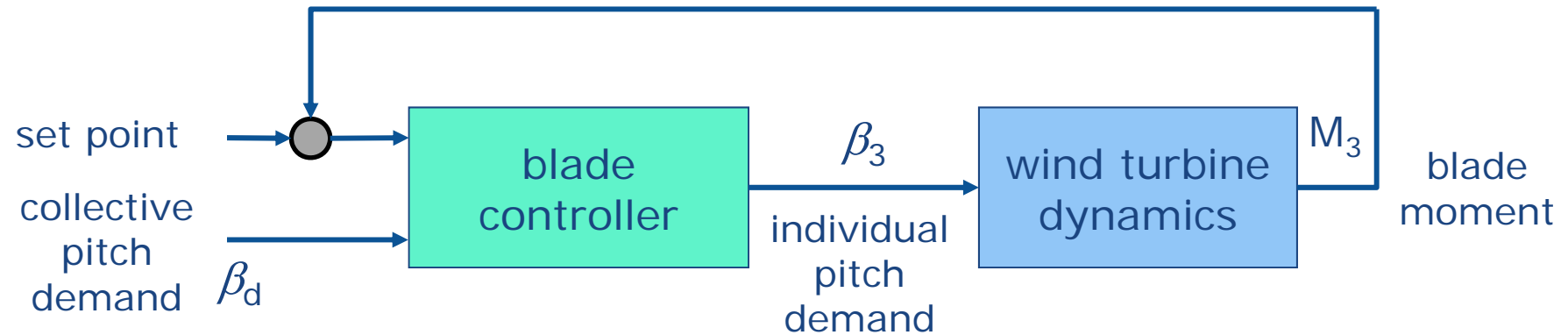
# Turbine Control Structure



# Turbine Control Structure

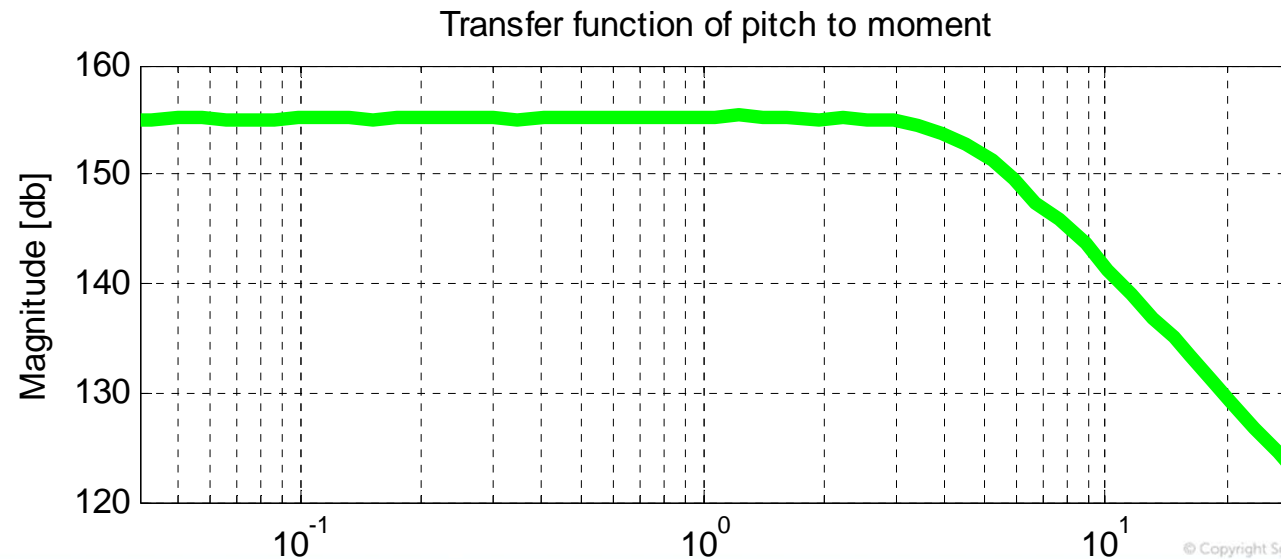
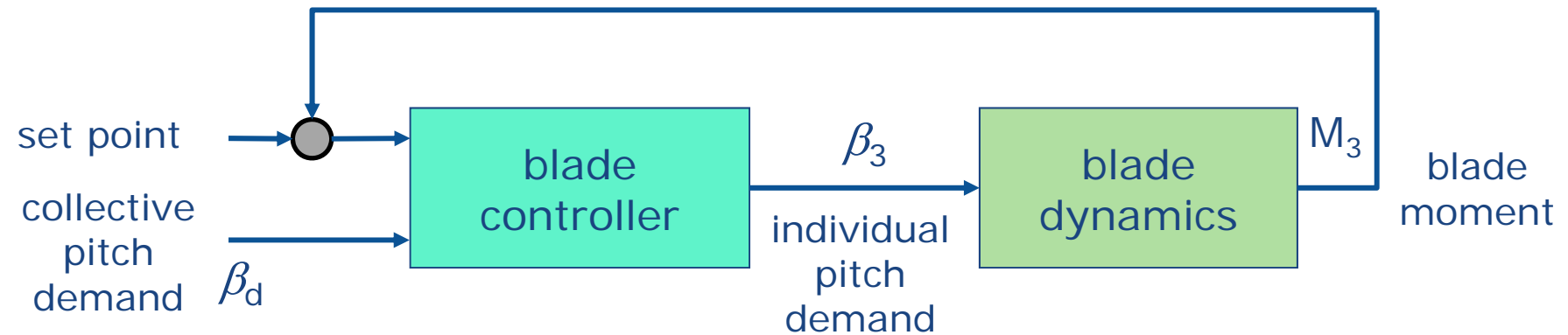


# Blade Control Design




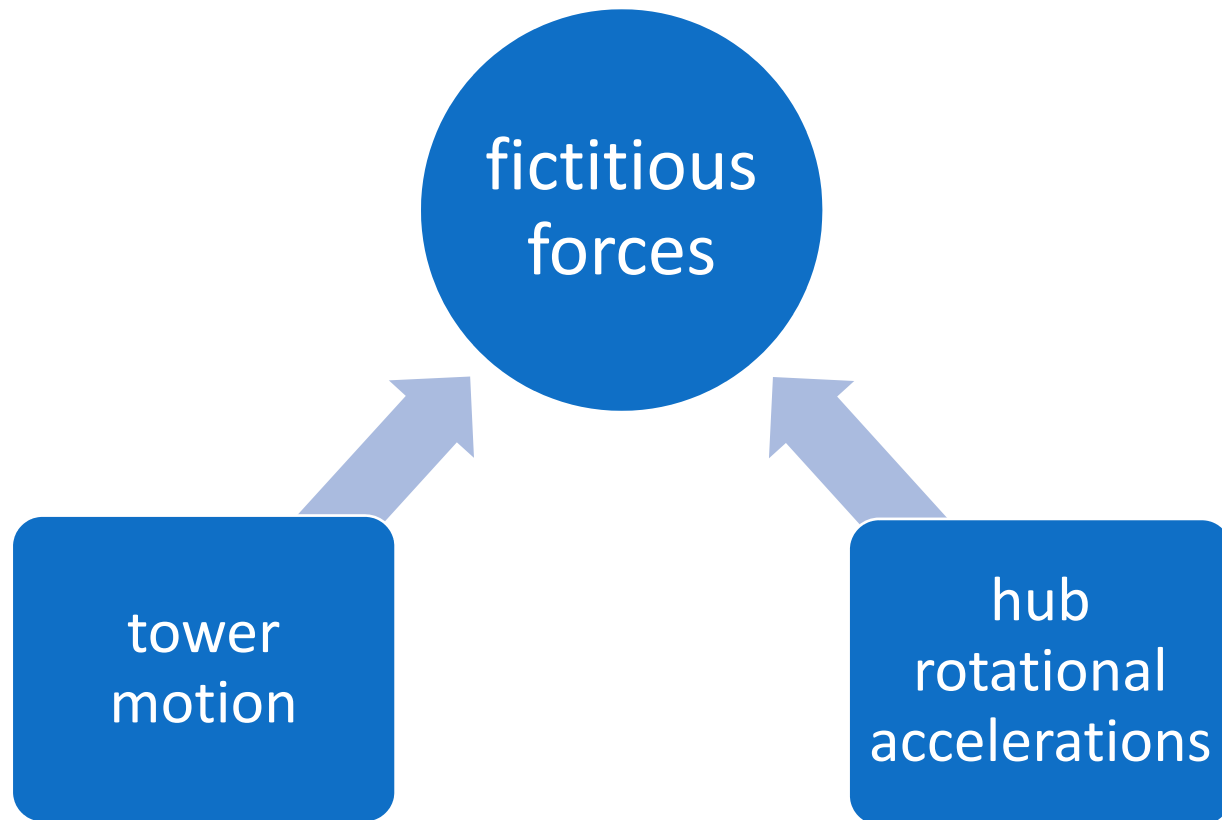


# Blade Control Design



# Fictitious Forces

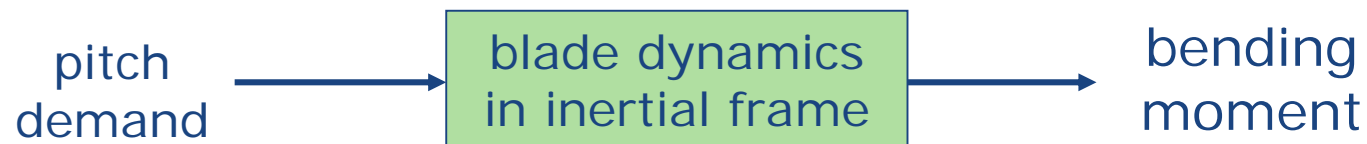
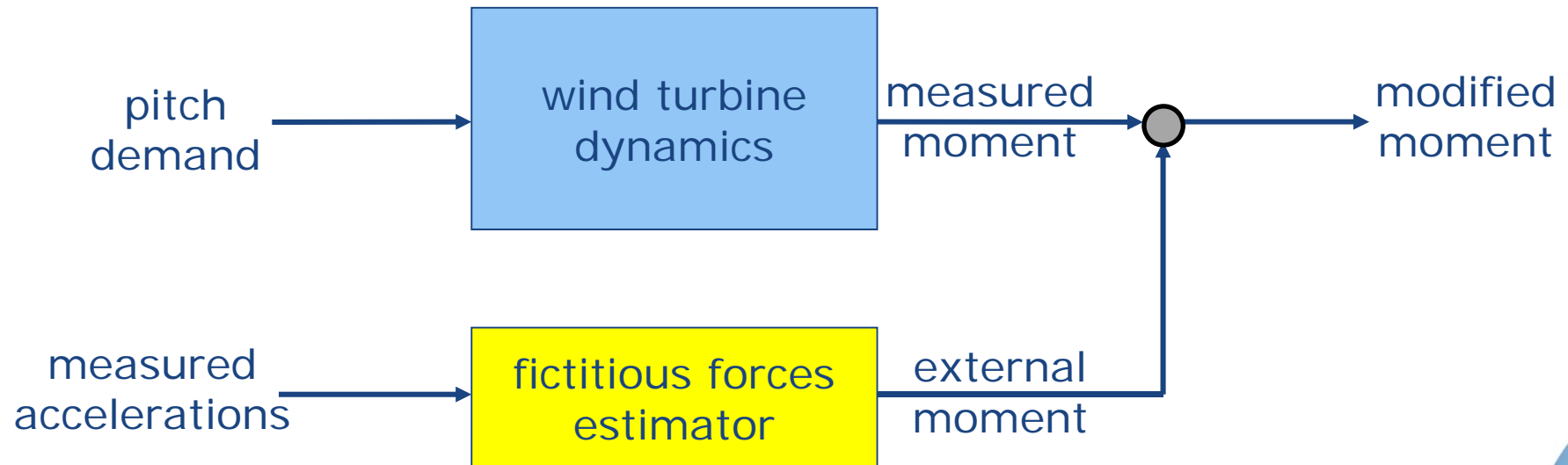
 A **fictitious force** is an apparent **force** that acts on all masses whose motion is described using a non-inertial frame of reference, such as a rotating reference frame.



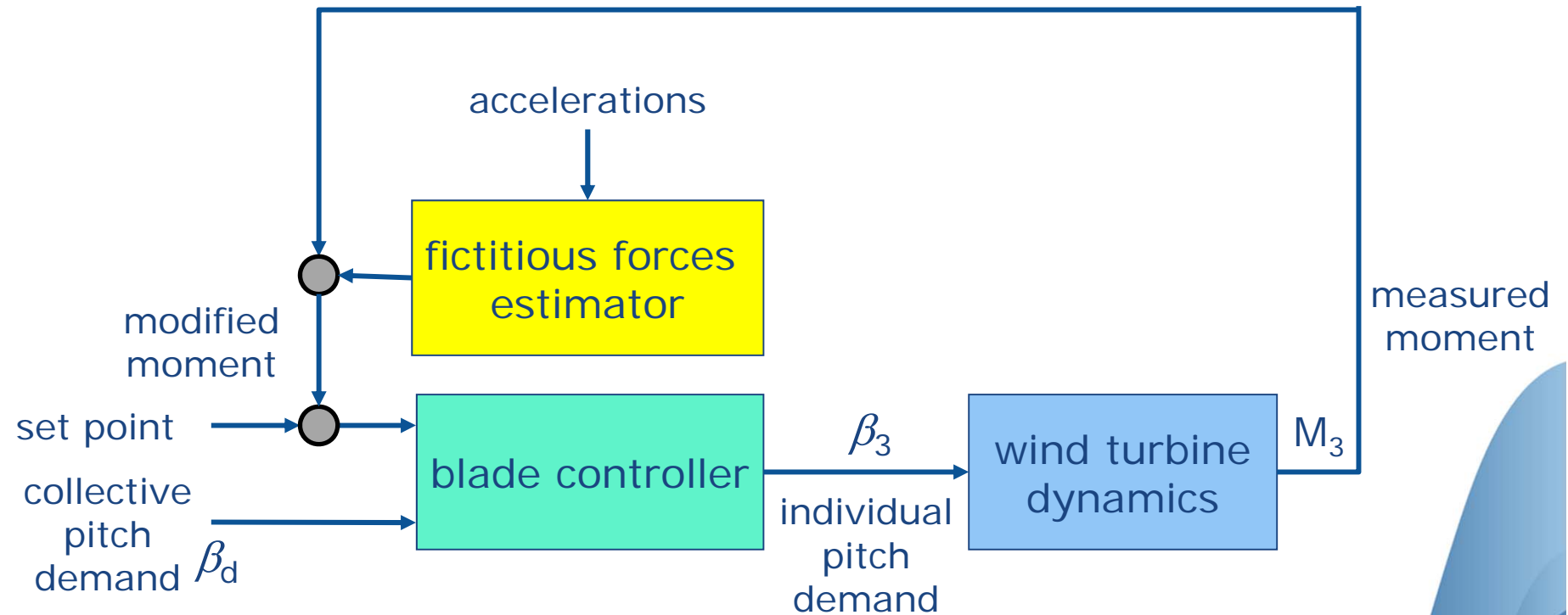
# Simplifying the Dynamics



# Simplifying the Dynamics

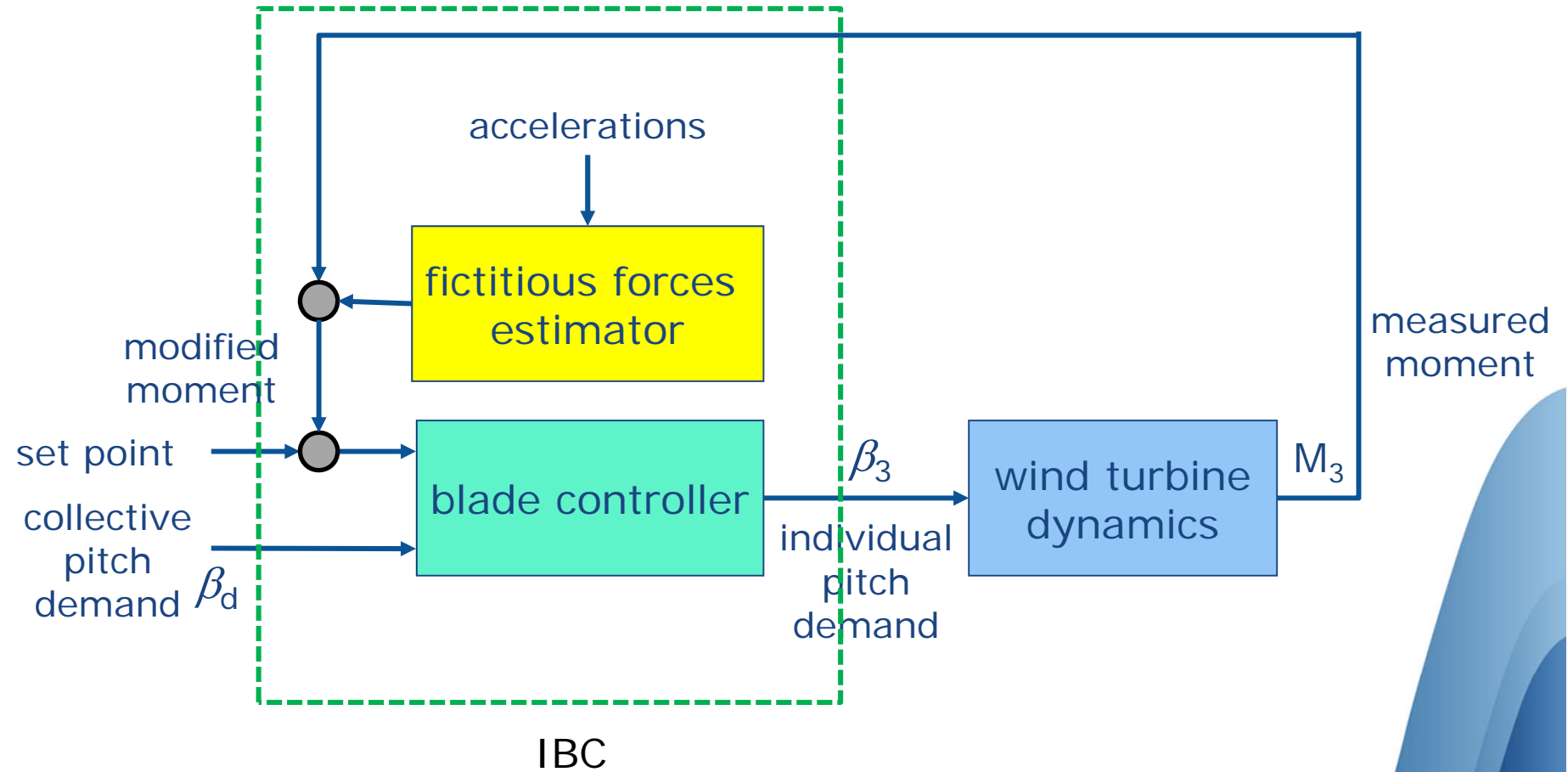


# IBC Structure

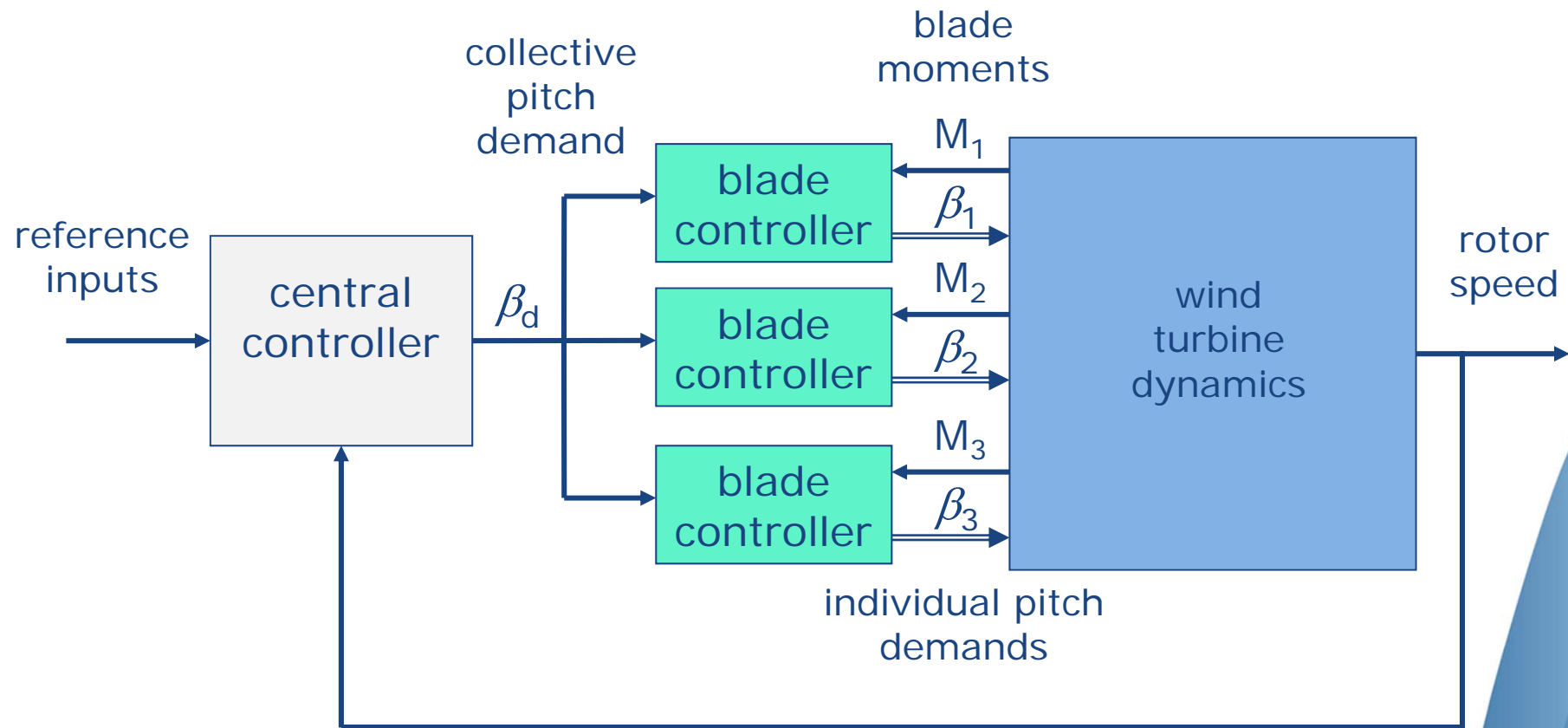




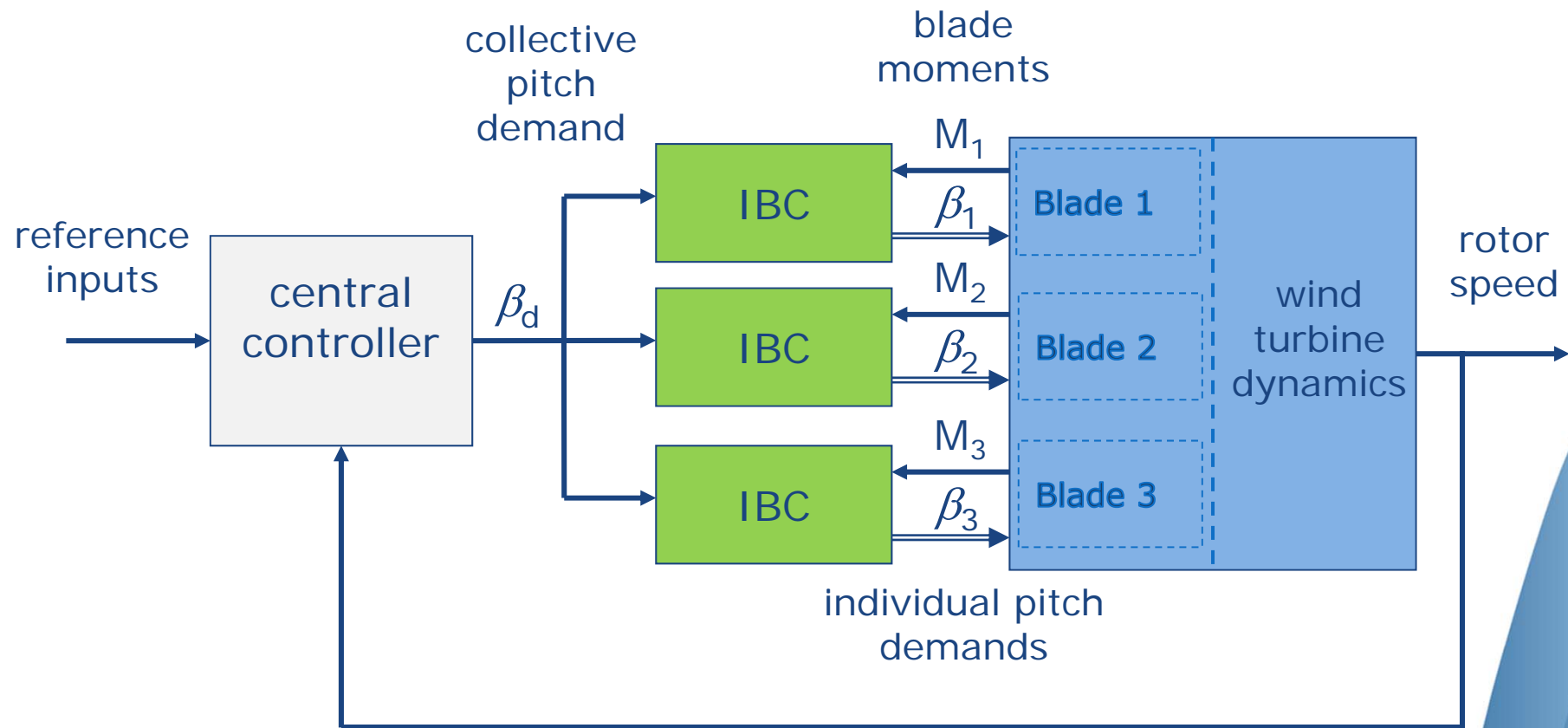
# IBC Structure



# Turbine Control Structure



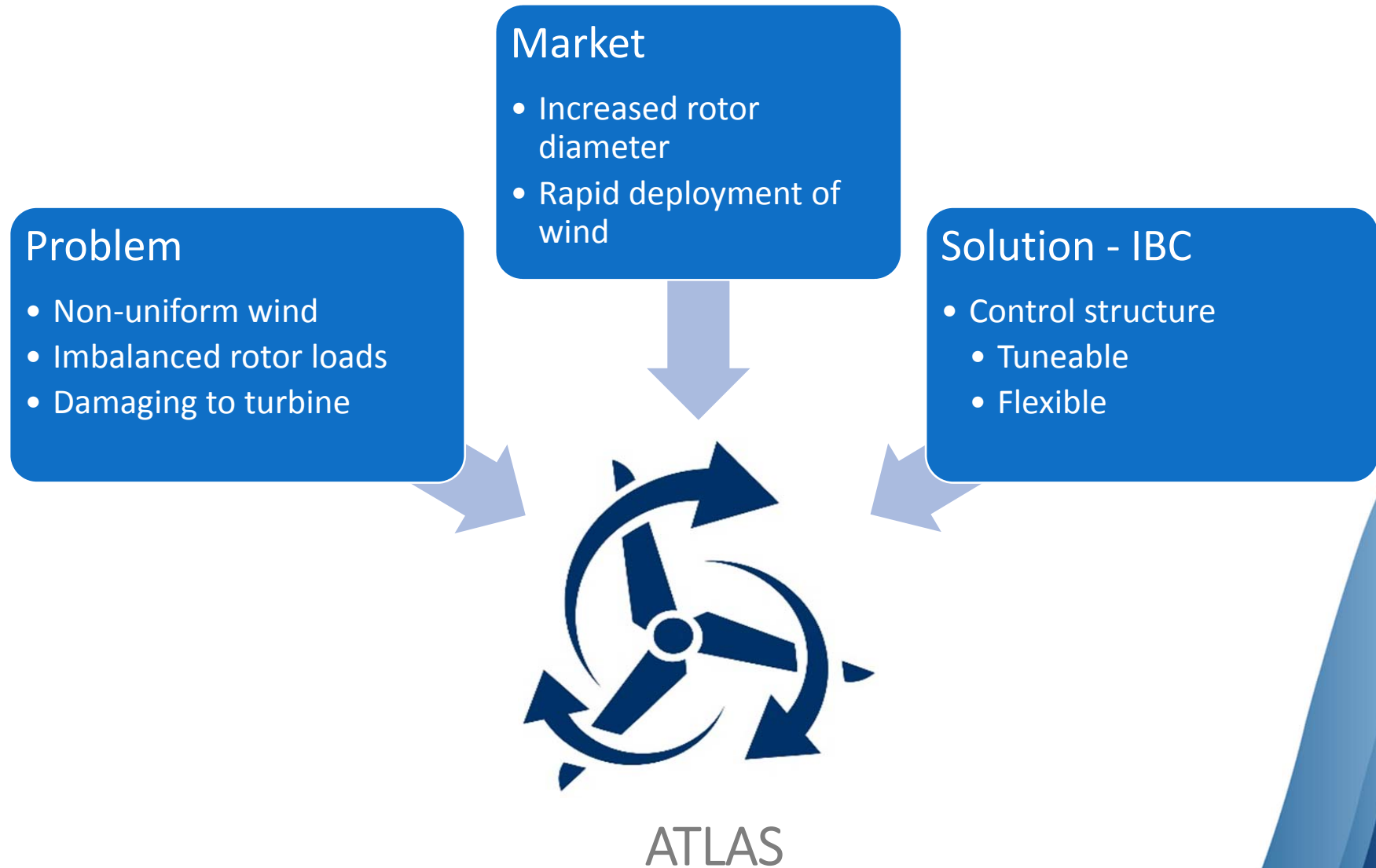
# Turbine Control Structure



# Advantages of IBC

- ~ Decoupled from turbine dynamics
- ~ Decentralised control
- ~ Transparent and straight forward to use
- ~ No loss of information
- ~ Has the flexibility to target critical loads
- ~ Optimise trade-off between load reduction and pitch activity
- ~ Target specific loadings at positions along the blades
- ~ Simple structure to implement

# The Product - ATLAS







Endpoints of diameter:  $(3,5)$  and  $(-1,-4)$ .

$$\left(\frac{x_1+x_2}{2}, \frac{y_1+y_2}{2}\right) \quad d = \sqrt{(x_2-x_1)^2 + (y_2-y_1)^2}$$

$$\left(\frac{3+(-1)}{2}, \frac{5+(-4)}{2}\right) \quad d = \sqrt{(5-(-1))^2 + (5-(-4))^2}$$

$$(1, \frac{1}{2}) \quad = \sqrt{4^2 + 9^2}$$

$$(h, k) \quad d = \sqrt{16+81} \Rightarrow r = \frac{\sqrt{97}}{2}$$

$$(x-h)^2 + (y-k)^2 = r^2$$

$$(x-1)^2 + (y-\frac{1}{2})^2 = \left(\frac{\sqrt{97}}{2}\right)^2$$

$$\therefore (x-1)^2 + (y-\frac{1}{2})^2 = \frac{97}{4}$$



Idea

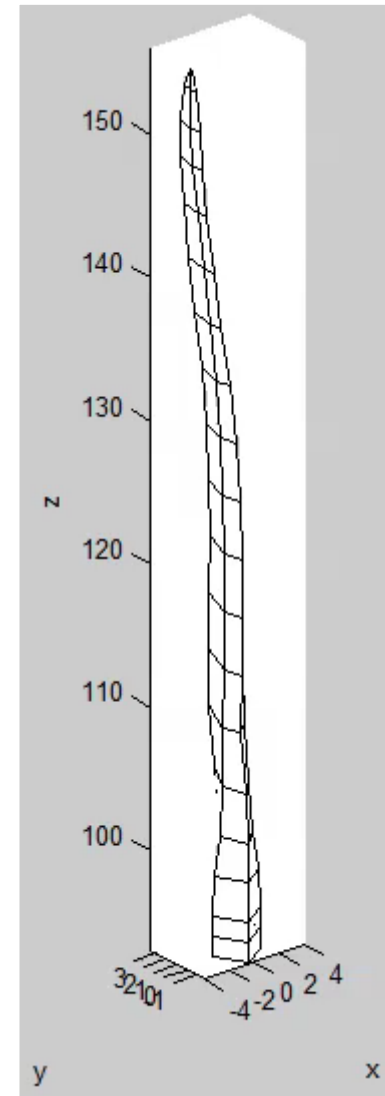
Development

Implementation

Demonstration

# ATLAS™ Individual Blade Control





- ⌚ Loads are the forces being applied onto the wind turbine component
- ⌚ Fatigue load – the aggregate effect that the forces would have on the structure over the whole lifetime
- ⌚ Extreme load – the abnormal and rare single event occurred at high level of force that the structure is generally designed to withstand



# ATLAS™ - Reducing Fatigue Load



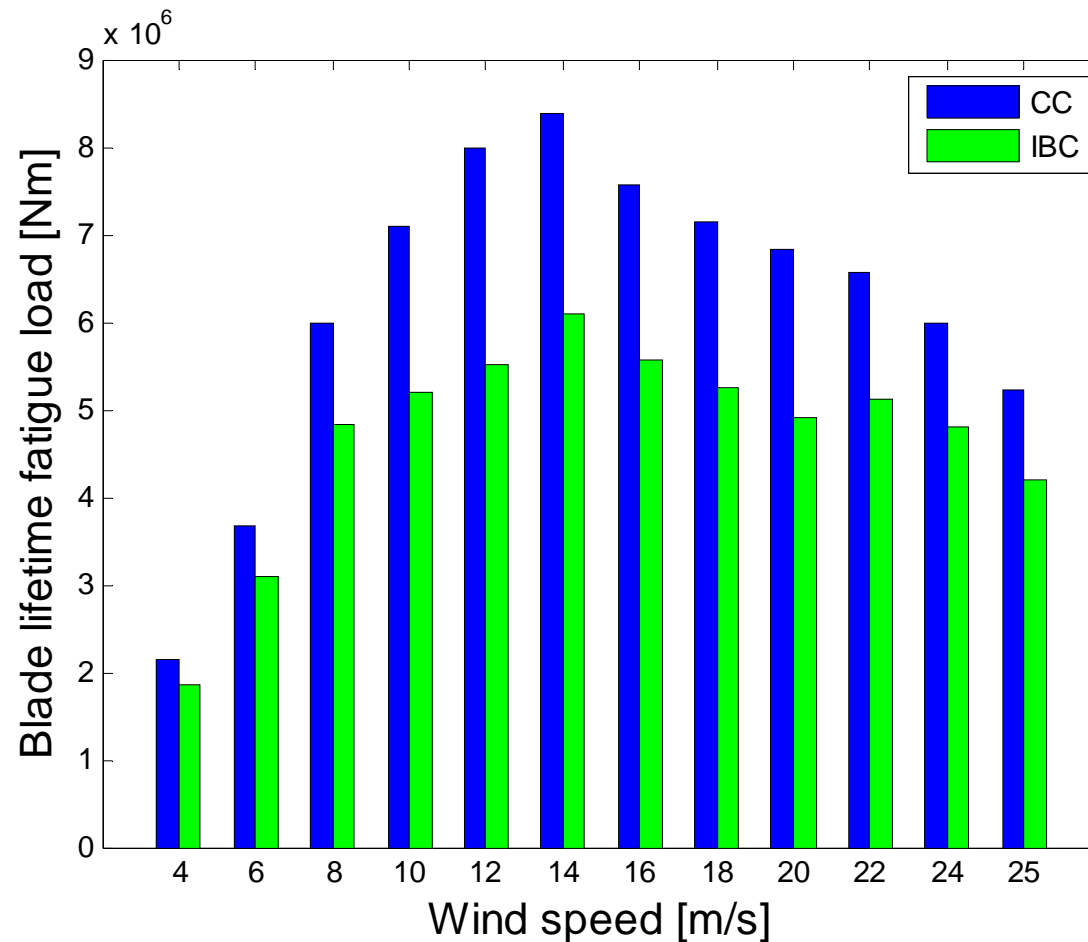
## Fatigue loads:

-  For the blades, the target component is out-of-plane bending moments
-  For the drive train, the target components are hub tilt and yaw moments
-  The main contribution is around the rated wind speed region where the wind turbine operates for most of the time
-  Assessed by lifetime (20 years) equivalent damage loads calculated through rain-flow counting



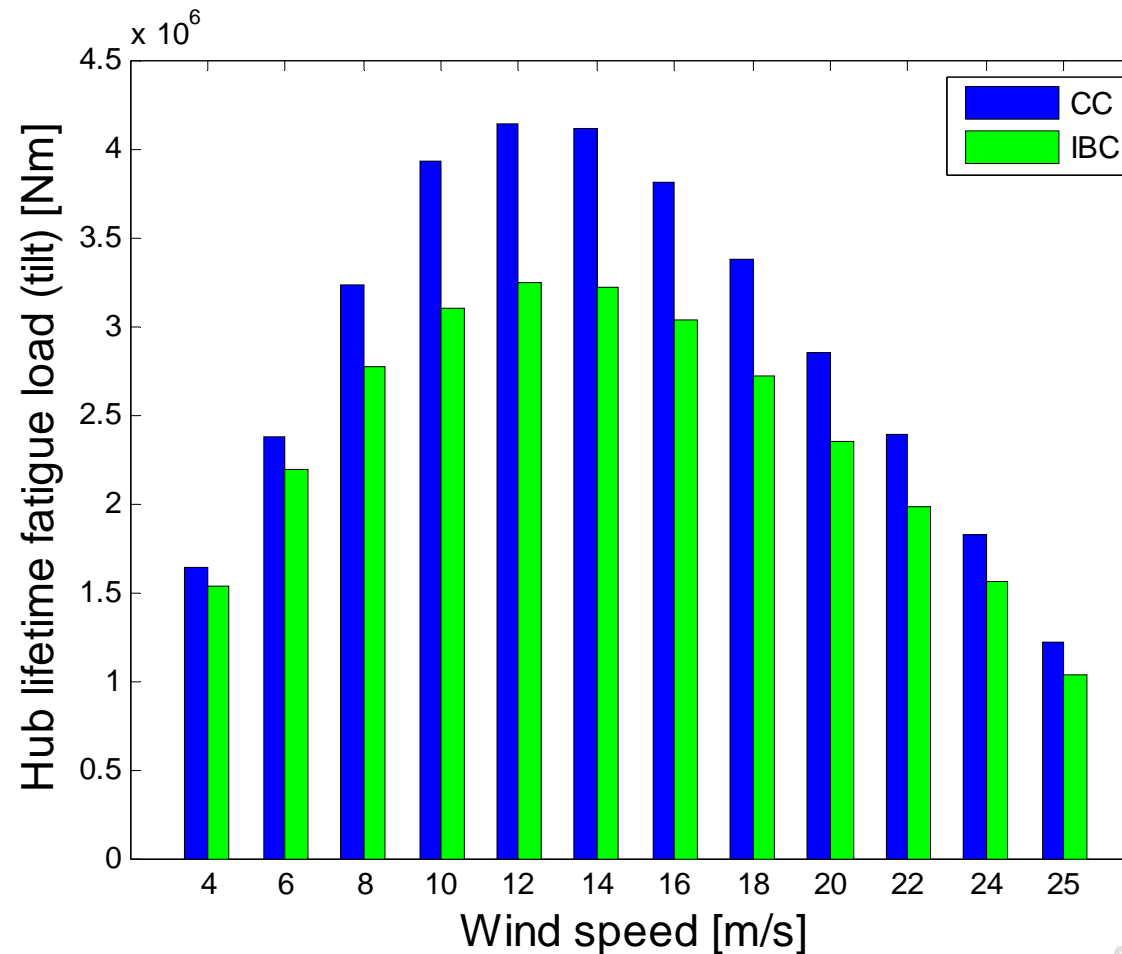
# ATLAS™ - Reducing Fatigue Load

 Reduction (~25%) on the blade lifetime fatigue damage



# ATLAS™ - Reducing Fatigue Load




 Reduction (~20%) on the hub lifetime fatigue damage

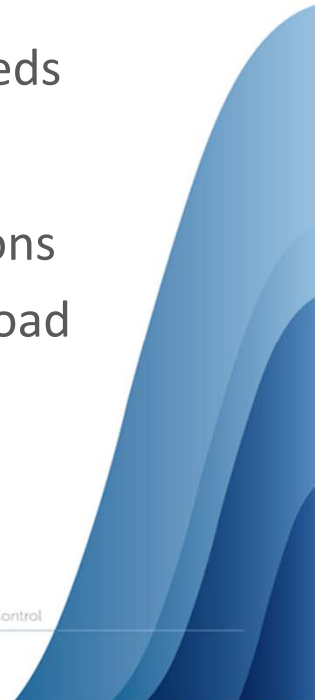


# ATLAS™ - Reducing Blade Extreme Load



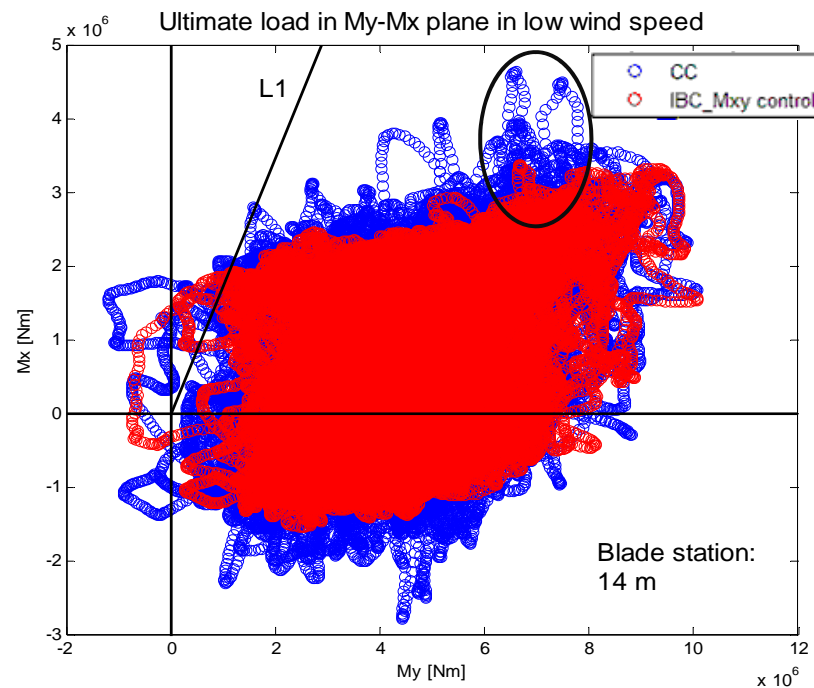
## Blade extreme loads:

-  Contributions from both blade in-plane ( $M_x$ ) and out-of-plane ( $M_y$ ) bending moments at various blade sections
-  Critical scenarios can occur at both low and high wind speeds
-  Assessed by projection of  $M_x$  and  $M_y$  onto specific directions in the ( $M_y, M_x$ ) plane at the instance when the maximum load arises

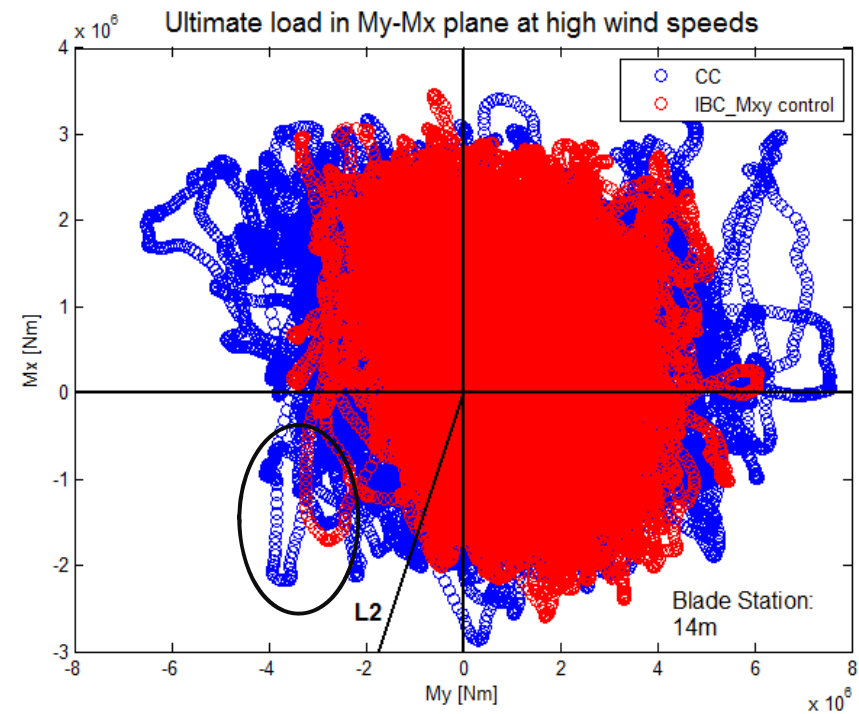


# ATLAS™ - Reducing Blade Extreme Load

## Reduction of extreme loads

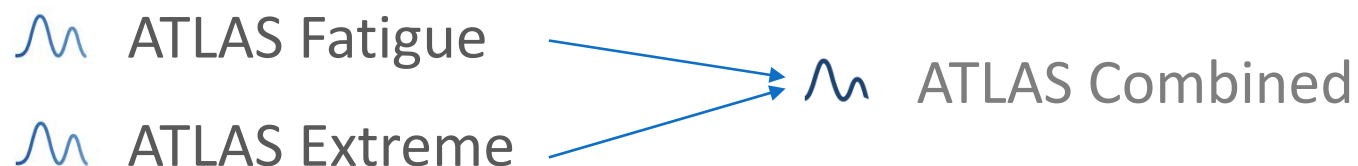


Critical load L1  
at low wind speed



Critical load L2  
at high wind speed

# ATLAS™ - Reducing the Load

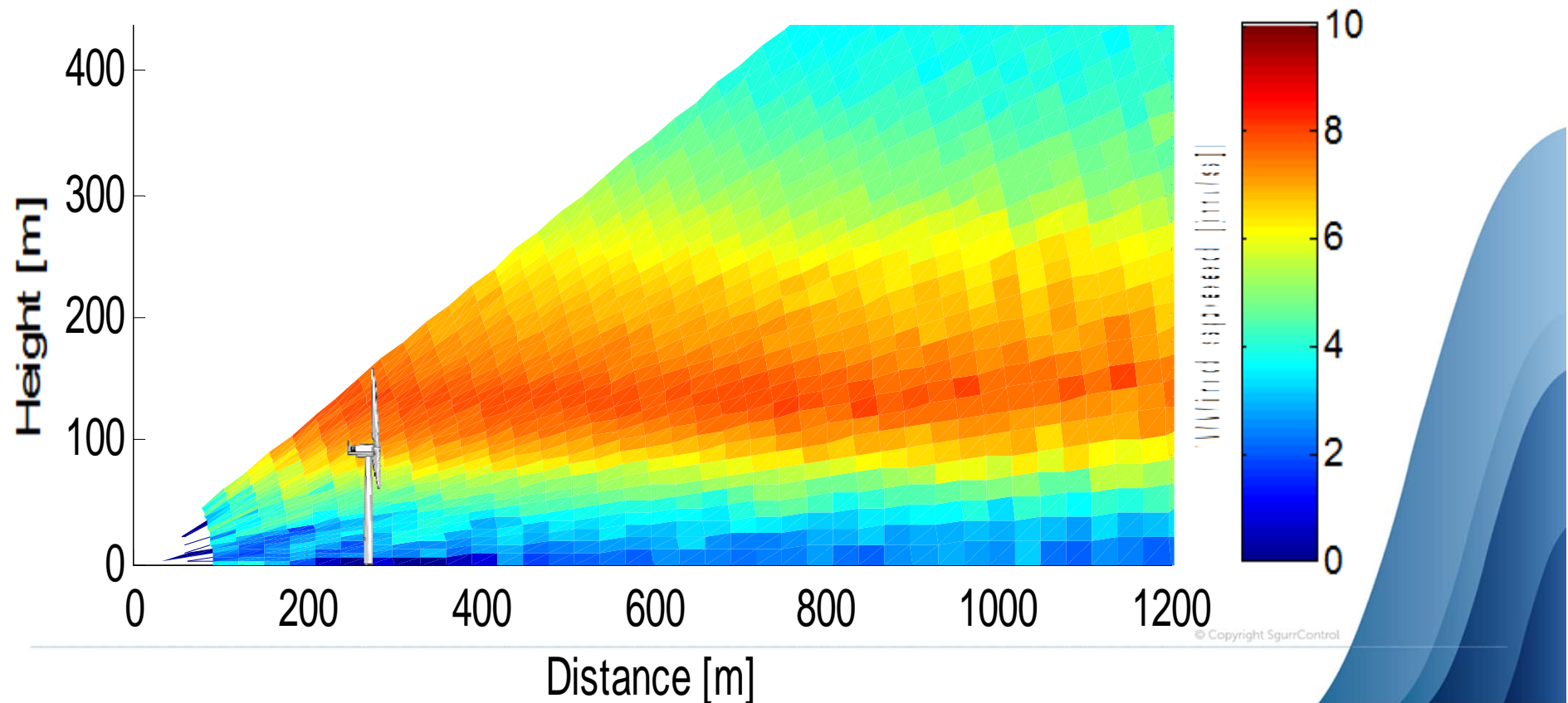


| Controller Designs | ATLAS Fatigue |      | ATLAS Extreme |      | ATLAS Combined |      |
|--------------------|---------------|------|---------------|------|----------------|------|
| Blade fatigue load | -27%          |      | 0             |      | -27%           |      |
| Hub fatigue load   | -20%          |      | 0             |      | -20%           |      |
| Tower fatigue load | -4%           |      | 0             |      | -3%            |      |
| Blade extreme load | L1            | L2   | L1            | L2   | L1             | L2   |
|                    | 0             | -14% | -33%          | -24% | -33%           | -24% |

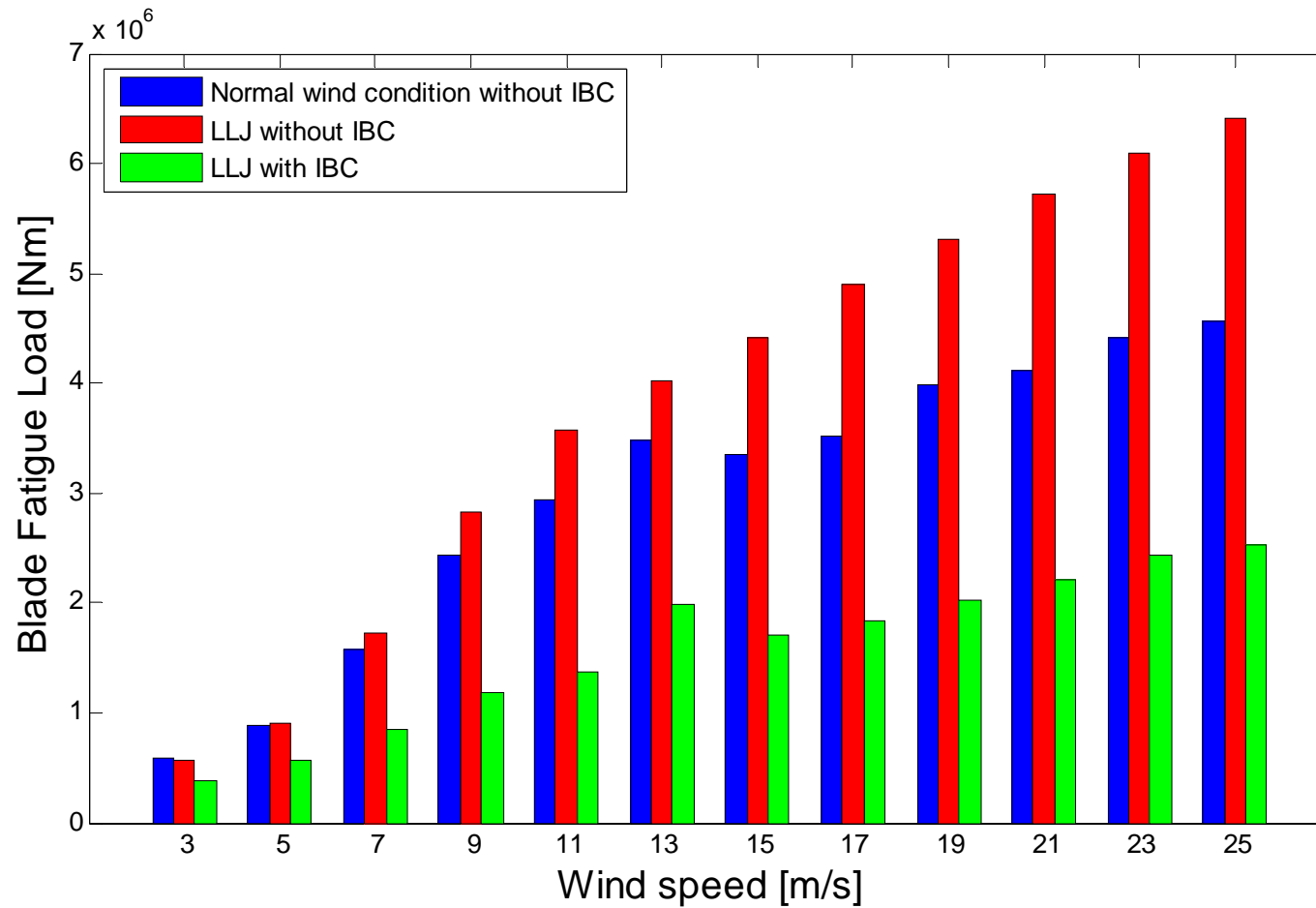



# ATLAS™ - Application for Low Level Jets

- Low Level Jet event – phenomenon observed shows the wind speed rising dramatically with the height
- Wind turbines have been experiencing higher loads and higher component failure rates



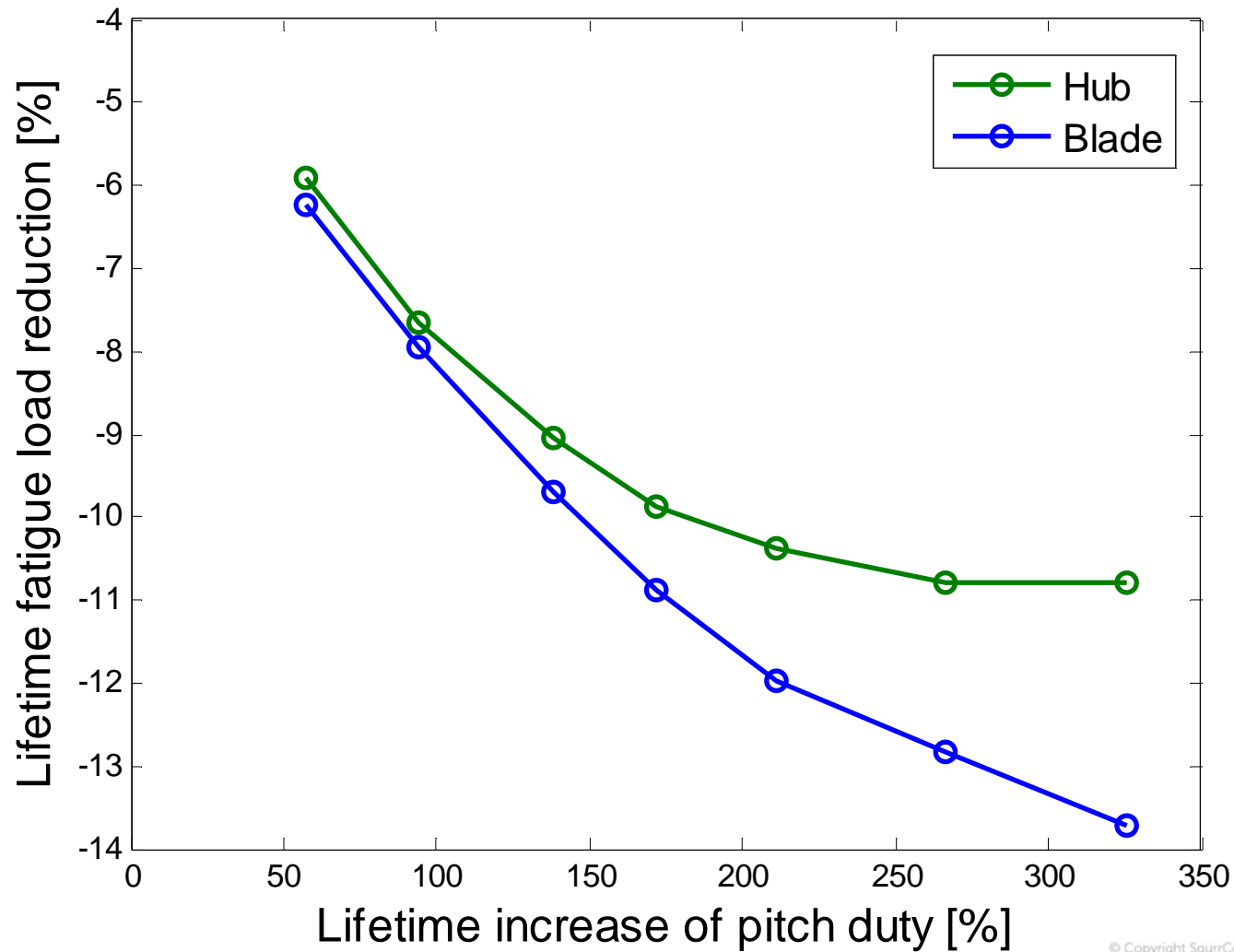
# ATLAS™ - Application for Low Level Jets



 Not only are the blade loads reduced, but also the loads on the hub and the shaft are reduced

# ATLAS™ - Pitch Trade-off

Investigation on pitch duty against load reduction





Endpoints of diameter  $(3,5)$  and  $(-1,-4)$

$$\left(\frac{x_1+x_2}{2}, \frac{y_1+y_2}{2}\right) \quad d = \sqrt{(x_1-x_2)^2 + (y_1-y_2)^2}$$

$$\left(\frac{3+(-1)}{2}, \frac{5+(-4)}{2}\right) \quad d = \sqrt{(3-(-1))^2 + (5-(-4))^2}$$

$$\left(\frac{1}{2}, \frac{1}{2}\right) \quad d = \sqrt{4^2 + 9^2}$$

$$(1, 1) \quad d = \sqrt{16+81} \Rightarrow d = \sqrt{97}$$

$$(2-1)^2 + (5-1)^2 = 16$$

$$(3-1)^2 + (5-1)^2 = 92$$

$$(3-1)^2 + (5-1)^2 = \frac{92}{4}$$



Idea

Development

Implementation

Demonstration

# ATLAS™ - Field Demonstration



- Field demonstration funded by the Department of Energy and Climate Change (DECC)
- Partner with Romax as an independent third party for analysis
- Field test and assessment on a Clipper C96 2.5MW wind turbine owned by University of Minnesota



# ATLAS™ - Field Demonstration



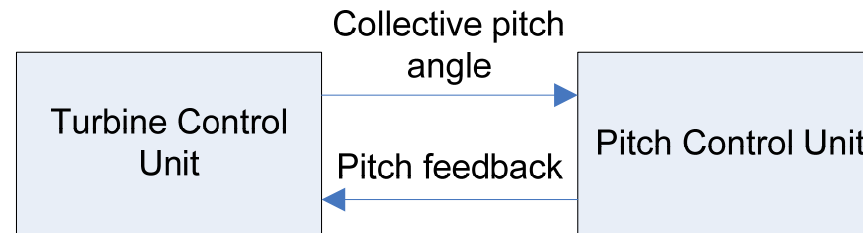
 Key aims:

-  Demonstration of the effectiveness of ATLAS in reducing the loads on a real turbine
-  Validation of the model and analysis and validation of the design process on a real turbine

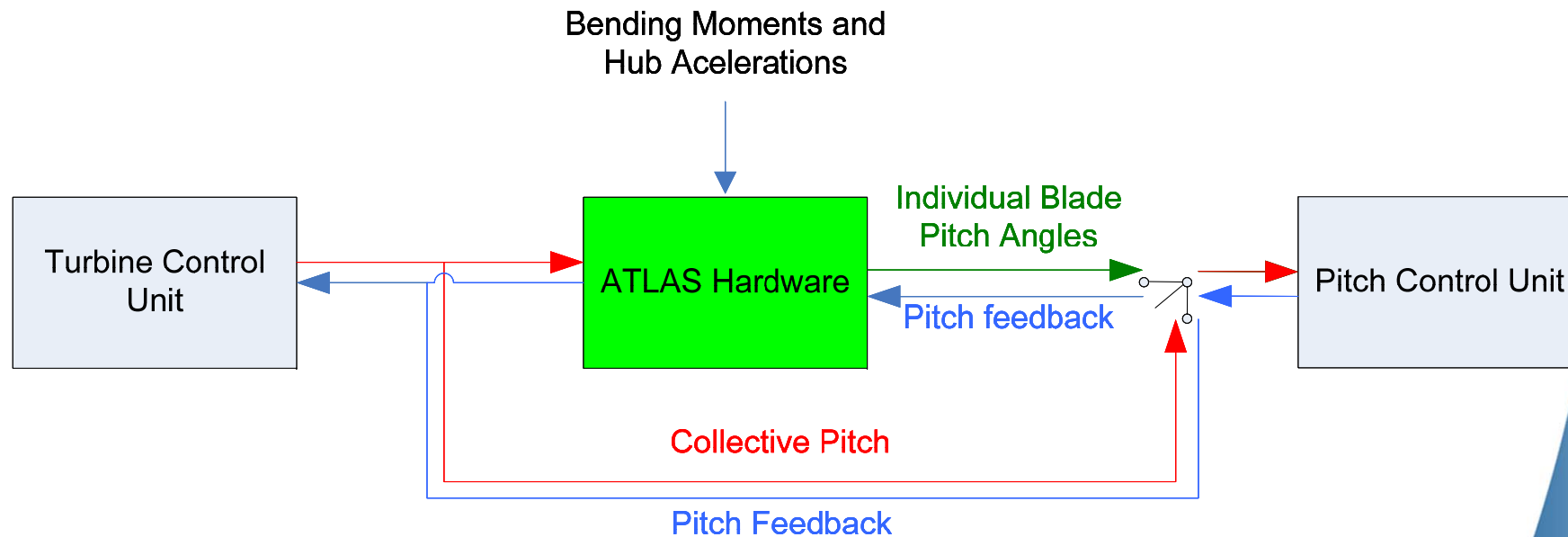


# Implementation Process

## Original turbine layout

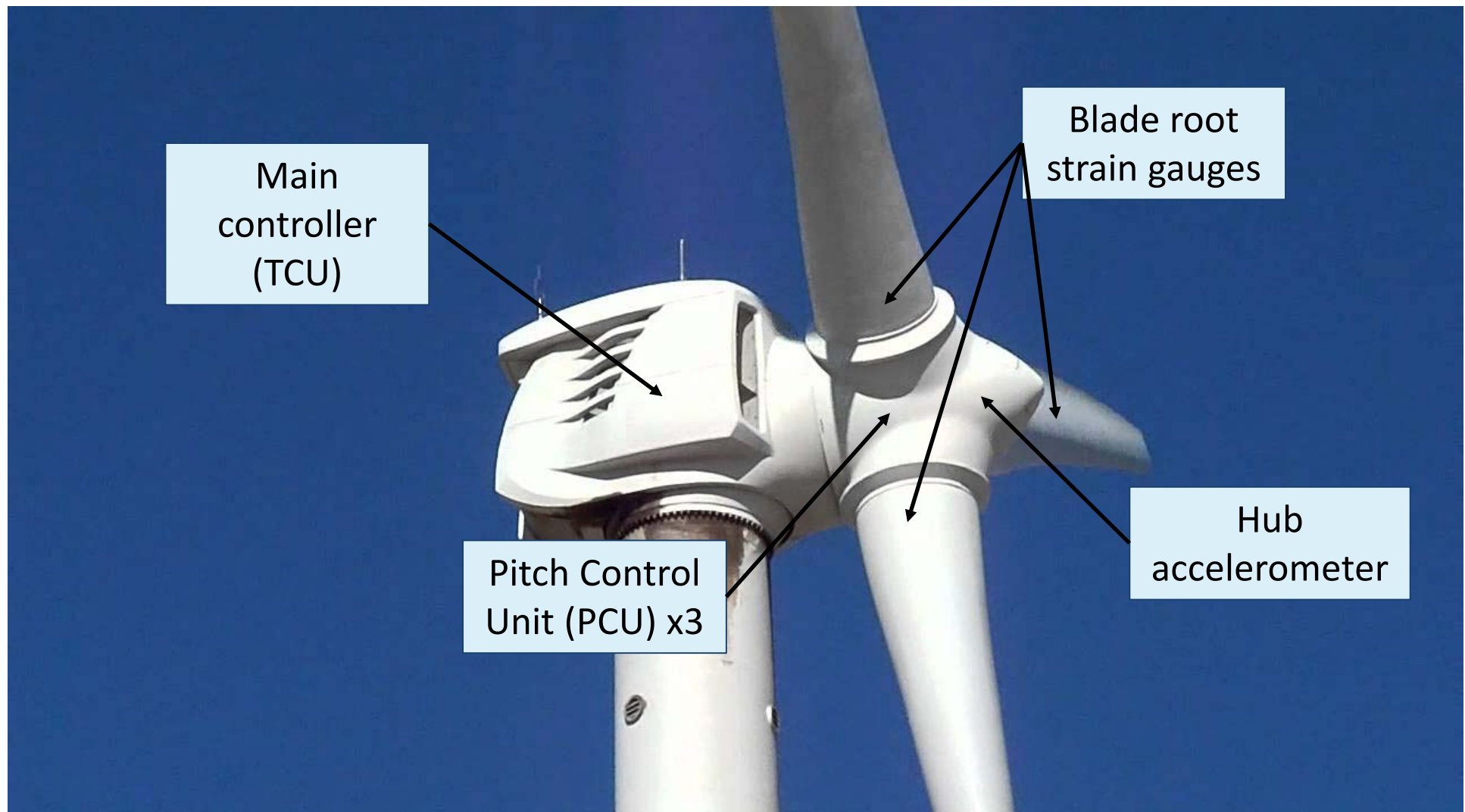


## ATLAS layout



# Implementation Process


Location of strain gauges and hub accelerometer

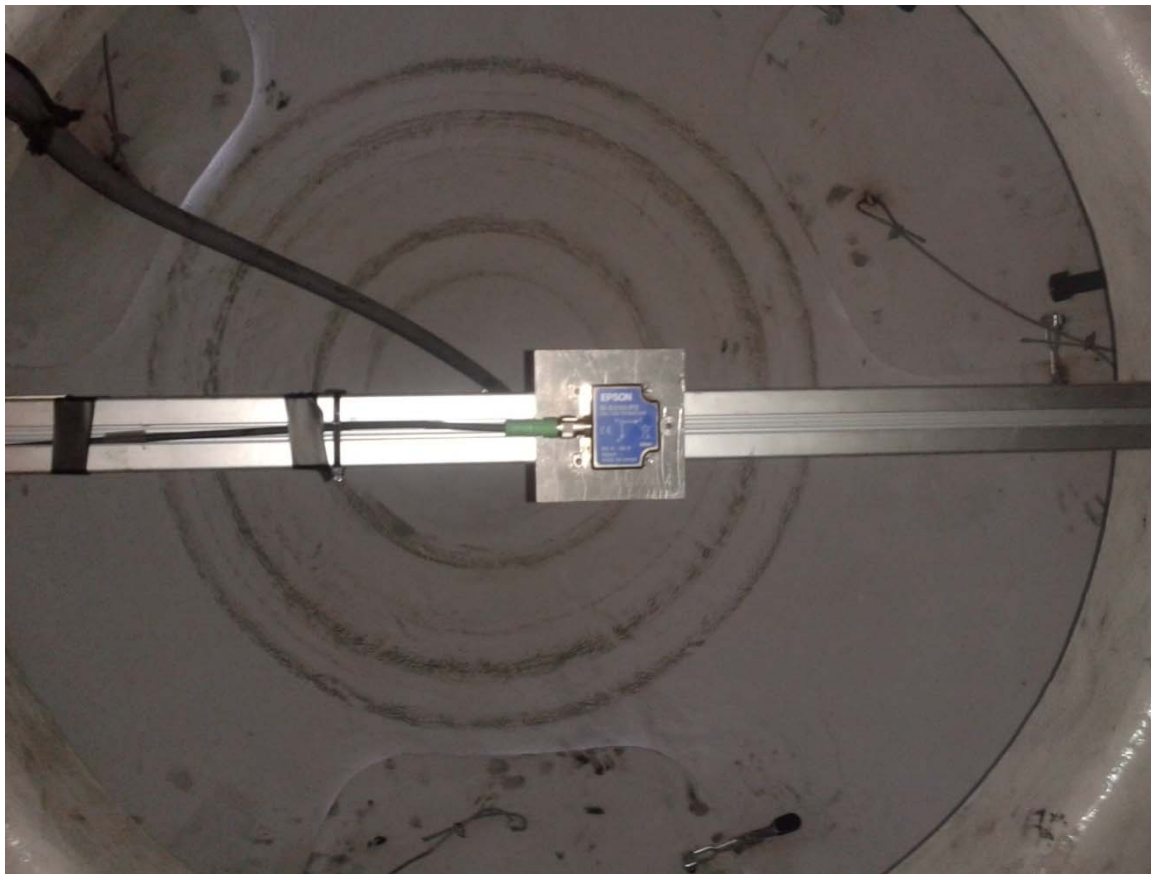




# Implementation Process

## Hardware configuration

 Requirements for the extra measurements - bending moments and hub accelerations



# Implementation Process

Three triaxial accelerometers to calculate angular rates



# Implementation Process

Installing the three triaxial accelerometers





# Implementation Process

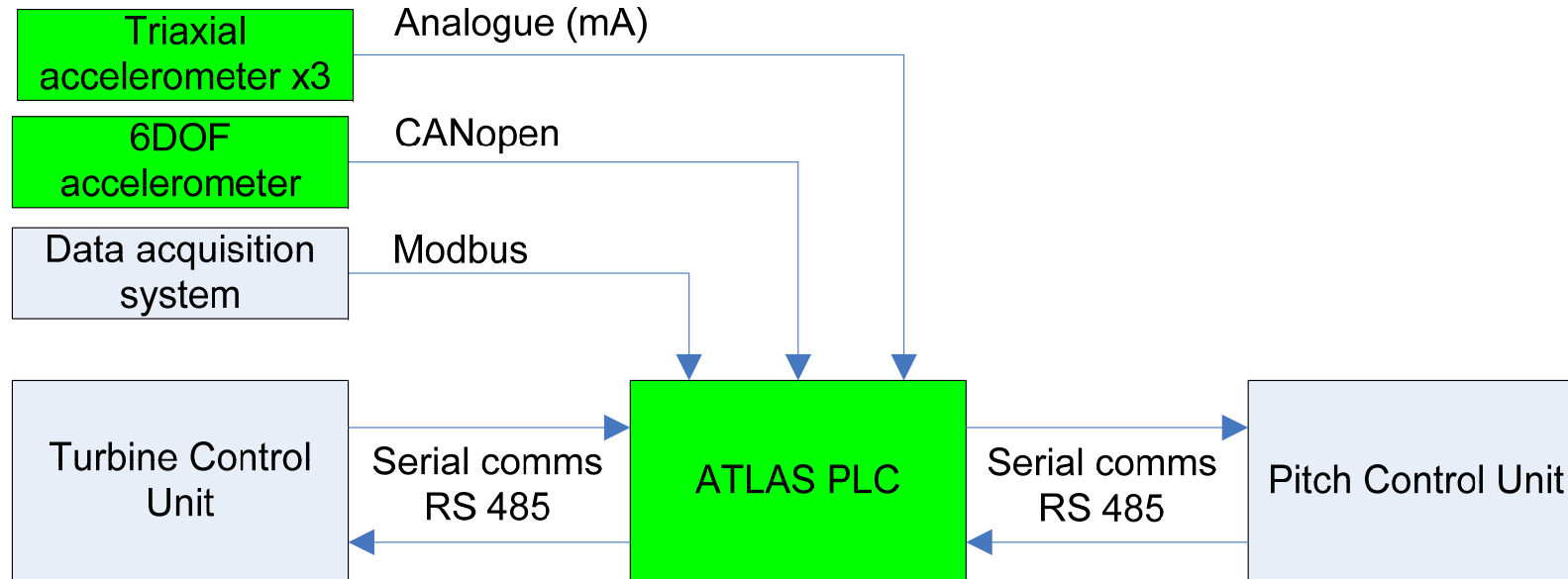
- Identifying the environmental constraints
- IP rating, temperature range, vibrations, etc.



# Implementation Process

## ⌚ Turbine Control Unit (TCU) requirements

### ⌚ Identifying the communication protocols



⌚ Feedback required from Pitch Control Unit (PCU) according to the command issued in the same cycle

⌚ The process of issuing commands and receiving an appropriate feed back should not take longer than 50ms

# Implementation Process

 Testing before deployment:

 Hardware in the loop (HiL)

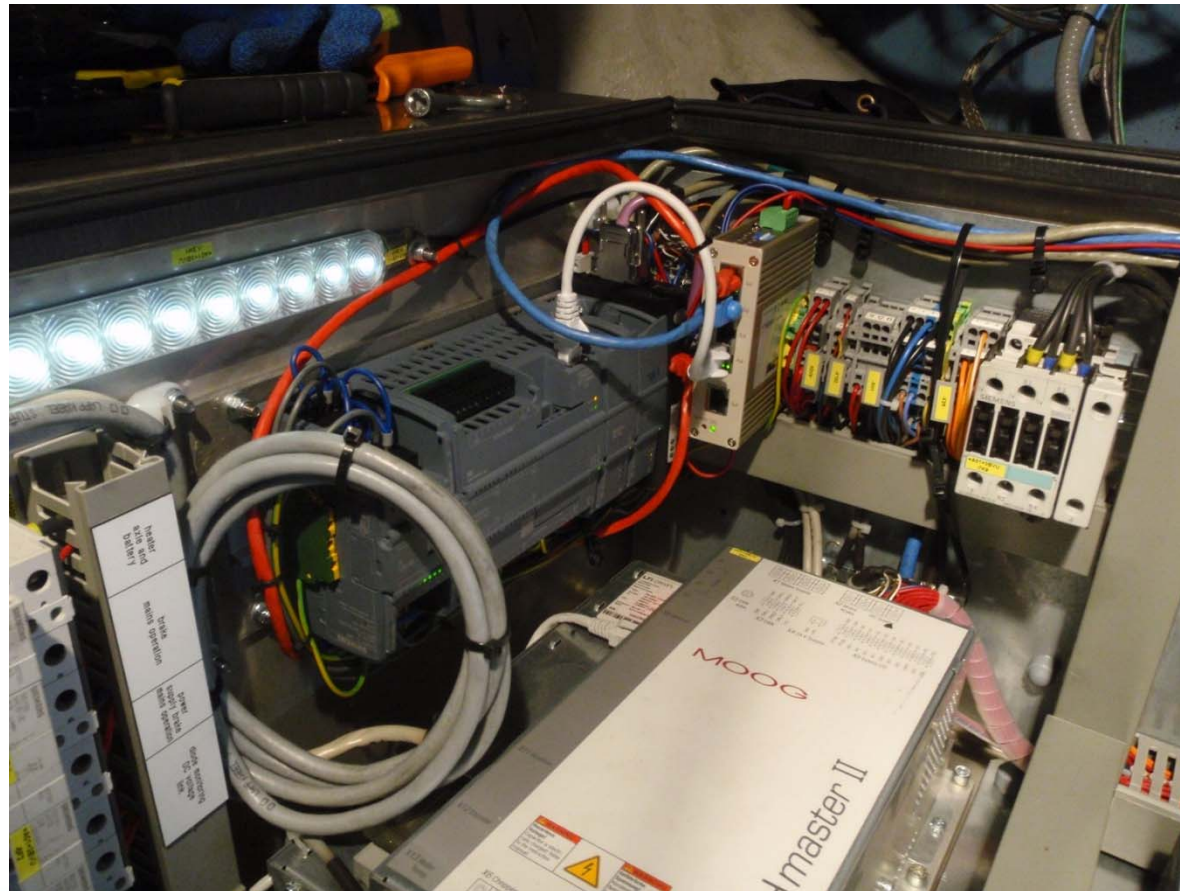
 Implementing extra alarms

 Testing the communications with the spare parts available

# Implementation Process

## Deployment stages




- ATLAS hardware mounted in the hub, tested to make sure it runs without any errors before connecting to TCU and PCU



# Implementation Process



## Deployment stages

-  ATLAS hardware connected to TCU and PCU and run as a bypass
-  Human Machine Interface (HMI) changed to provide the capability to enable/disable ATLAS
-  ATLAS enabled, controlling each blade individually





Endpoints of diameter  $(3, 5)$  and  $(-1, -7)$

$$\left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2} \right) \quad d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

$$\left( \frac{3 + (-1)}{2}, \frac{5 + (-7)}{2} \right) \quad d = \sqrt{(3 - (-1))^2 + (5 - (-7))^2}$$

$$\left( 1, -1 \right) \quad d = \sqrt{4^2 + 12^2}$$

$$\quad \quad \quad d = \sqrt{16 + 144} \Rightarrow d = \sqrt{160} \Rightarrow d = \frac{4\sqrt{10}}{2}$$

$$(x - h)^2 + (y - k)^2 = r^2$$

$$(x - 1)^2 + (y - (-1))^2 = \left( \frac{4\sqrt{10}}{2} \right)^2$$

$$(x - 1)^2 + (y + 1)^2 = \frac{160}{4}$$



Idea

Development

Implementation

Demonstration

# Demonstration - Main Objectives:

📈 Test the effectiveness of ATLAS → Does it work ?

📈 Reduce blade loads

📈 Does not interfere with speed controller

📈 Same energy capture

📈 Validate the model results → Does it work as supposed to?

📈 Same blade load reduction

📈 Same pitch activity



📈 Predict the lifetime benefits of ATLAS on a wind turbine

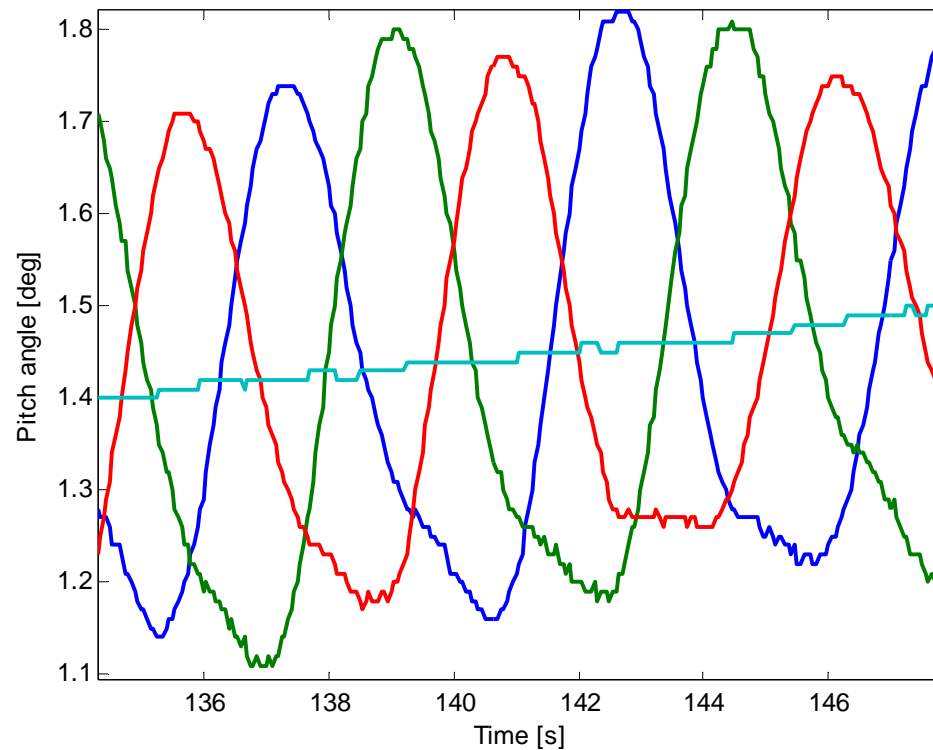


# Demonstration

## Commissioning

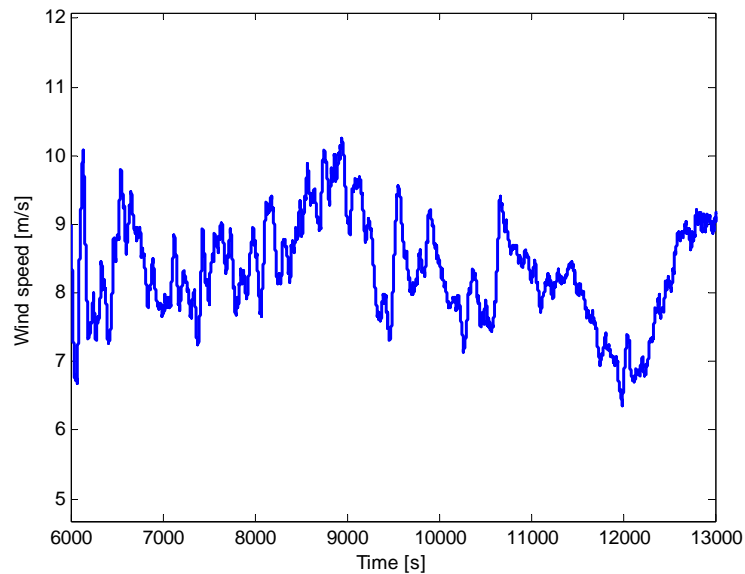
What do I need to test ATLAS?

Reduced gain controller & running under safe conditions



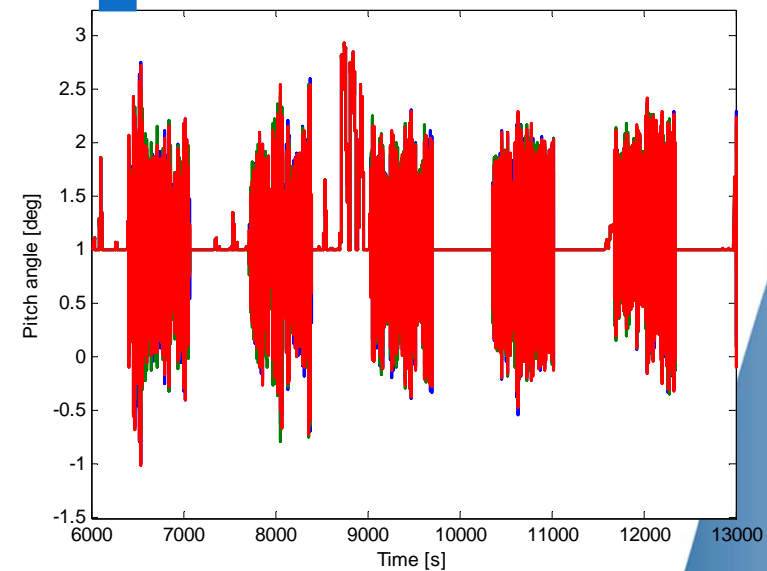
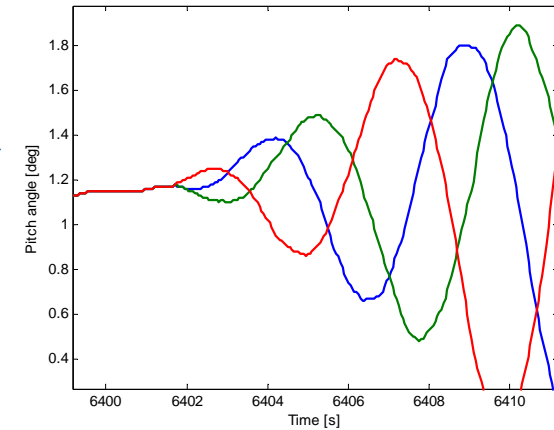
# Experimental Campaign

- Compare collective/ ATLAS
- Similar conditions
- 11 minutes on/off




Wind Speed

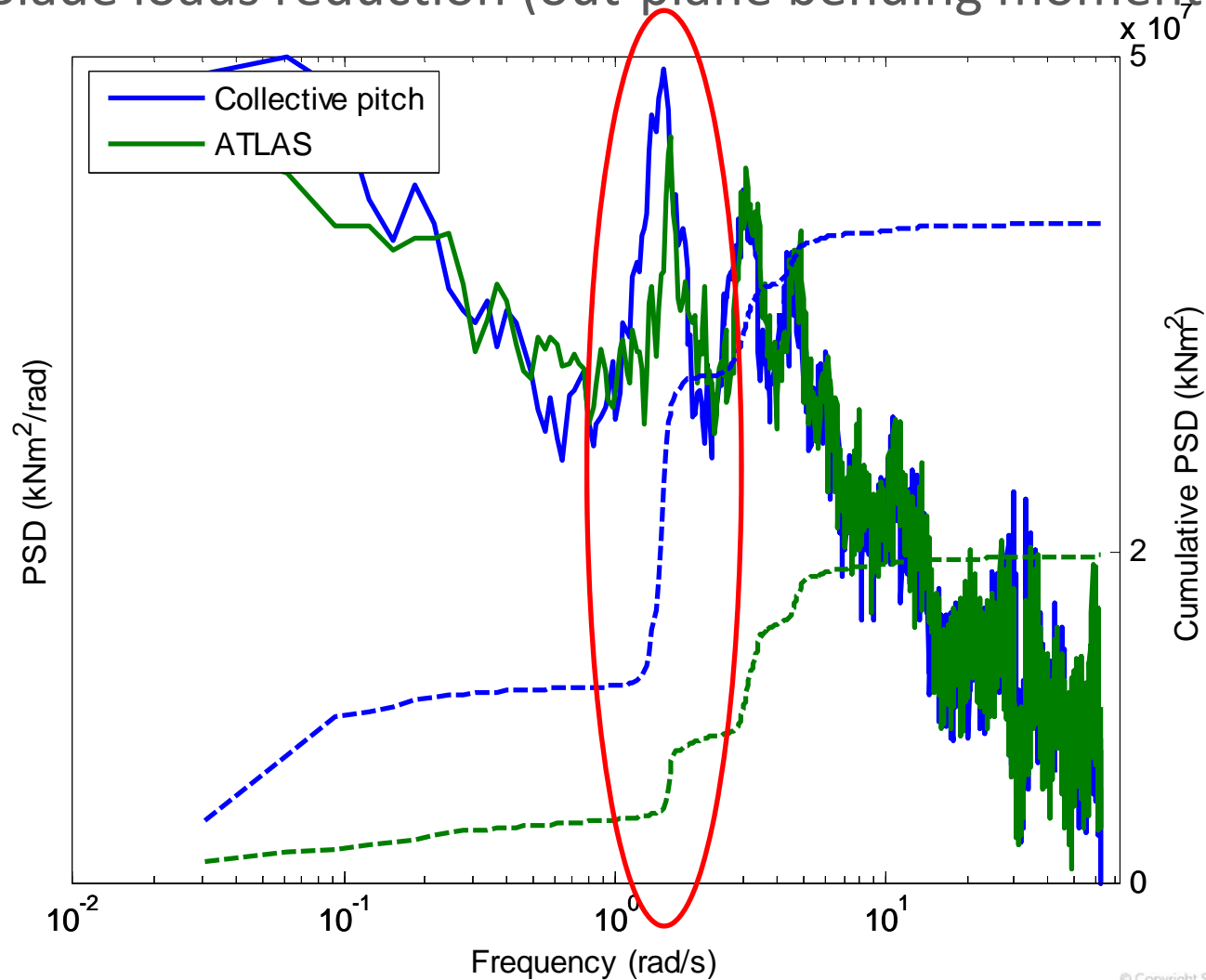
## Smooth switching



Pitch Angles

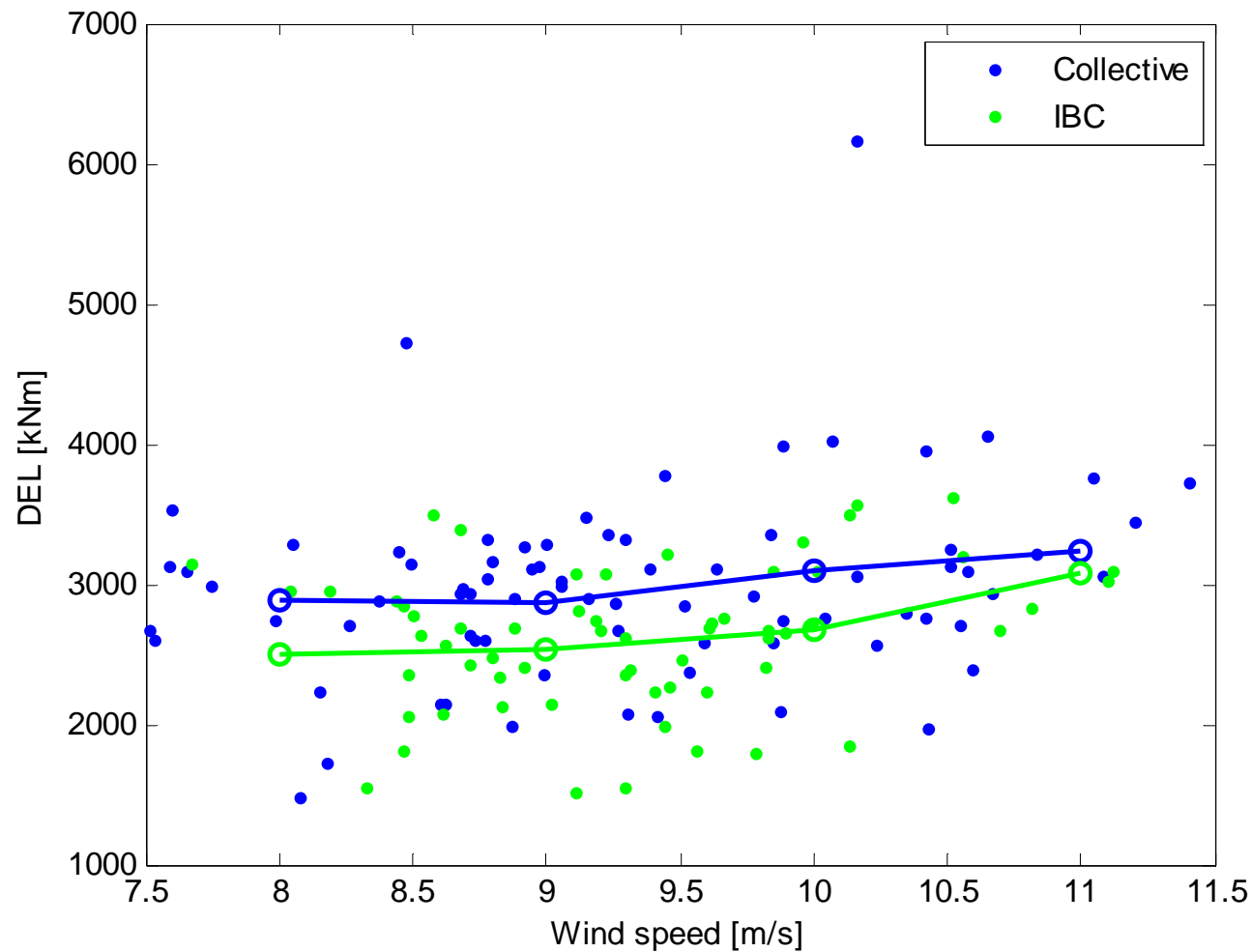
# Experimental Campaign - Results

 Blade loads reduction (out-plane bending moment)



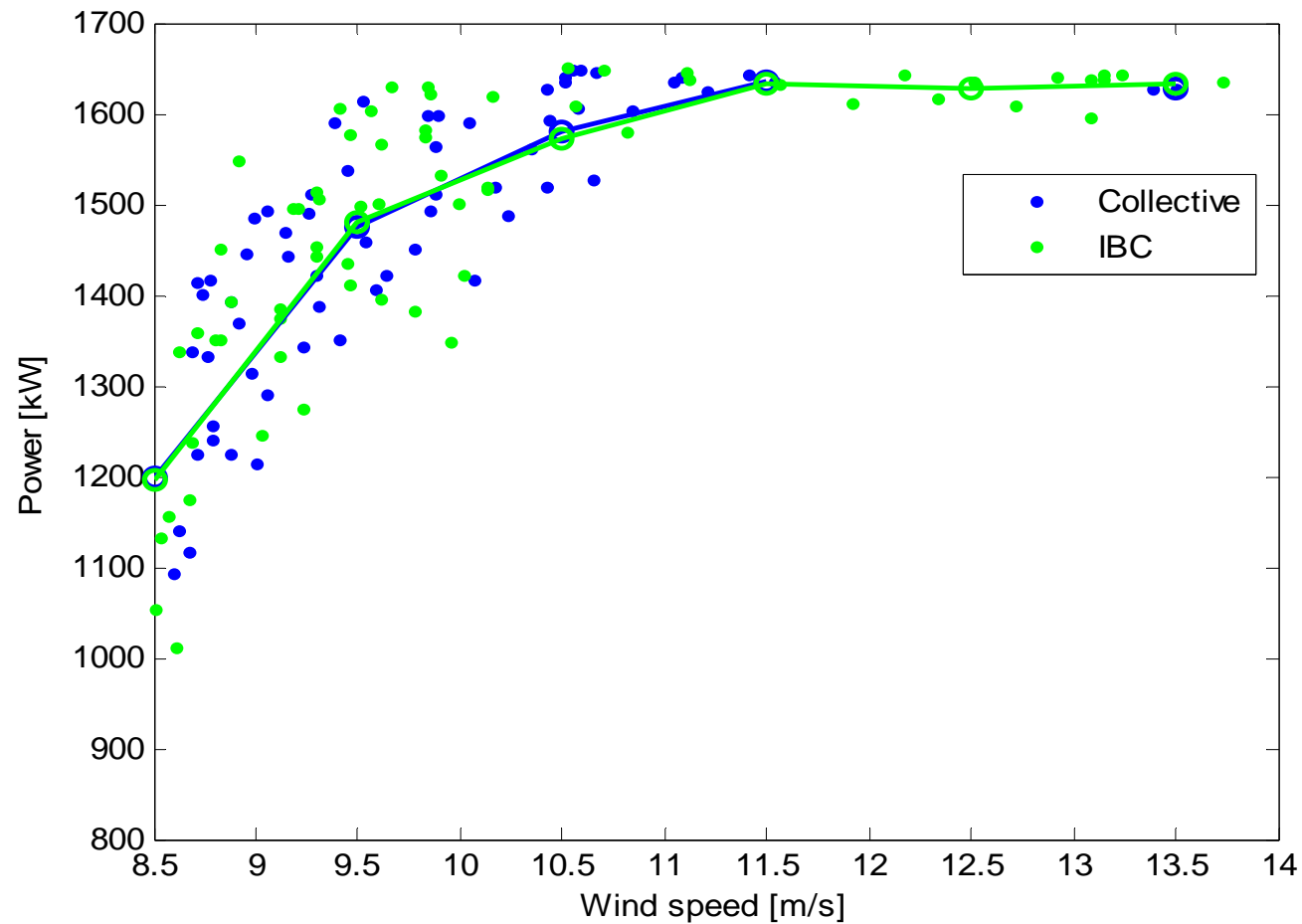
# Experimental Campaign - Results

 Blade loads reduction (out-plane bending moment)



# Experimental Campaign - Results

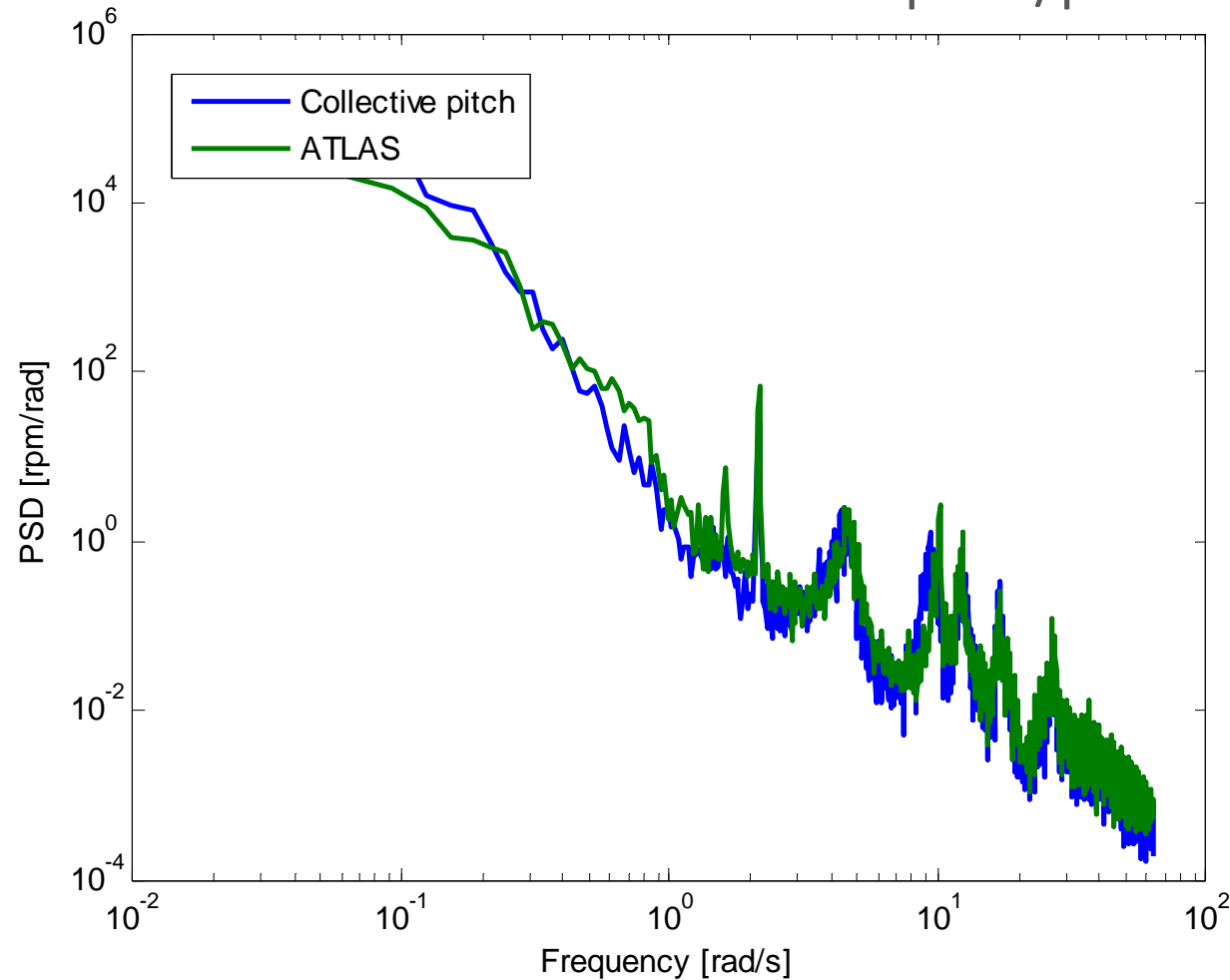
ATLAS does not interfere with the speed/power control



Power curve

# Experimental Campaign - Results

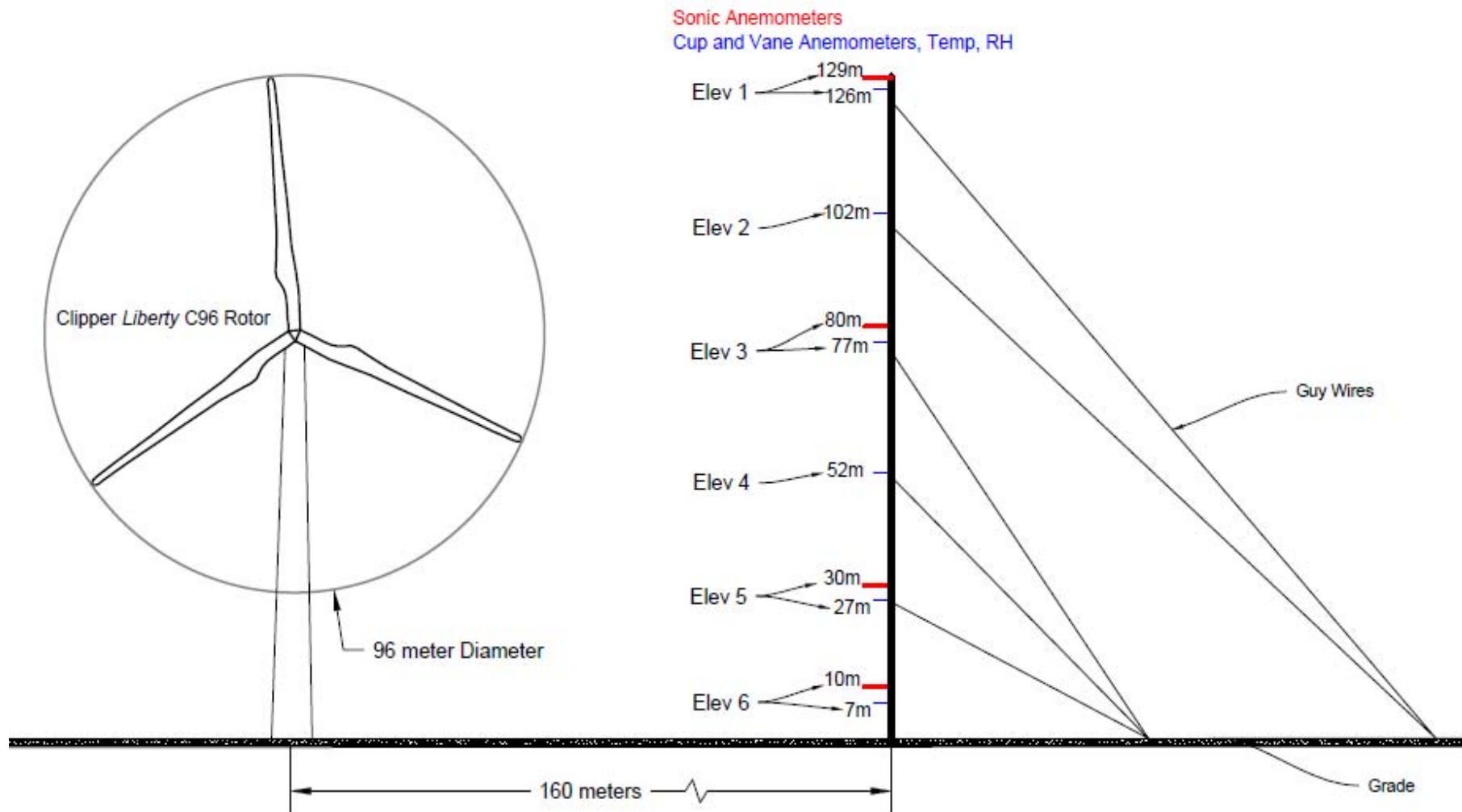
 ATLAS does not interfere with the speed/power control



Generator speed spectrum



# Model Validation

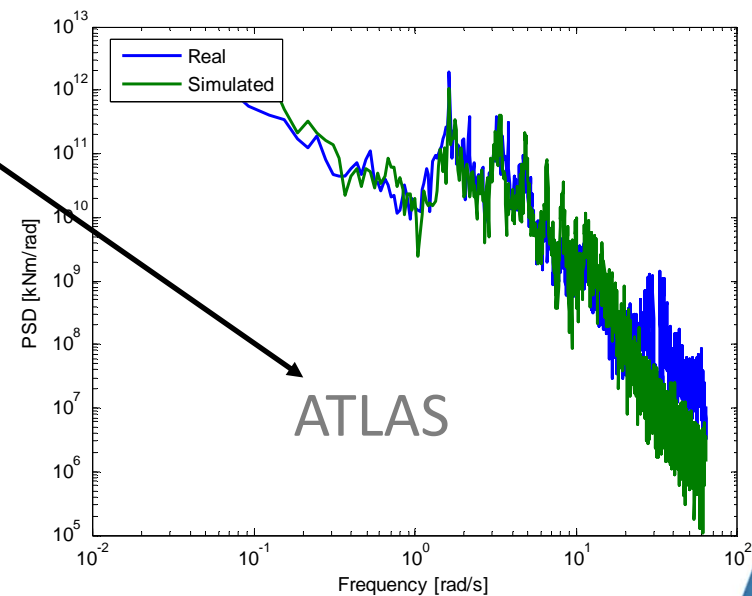
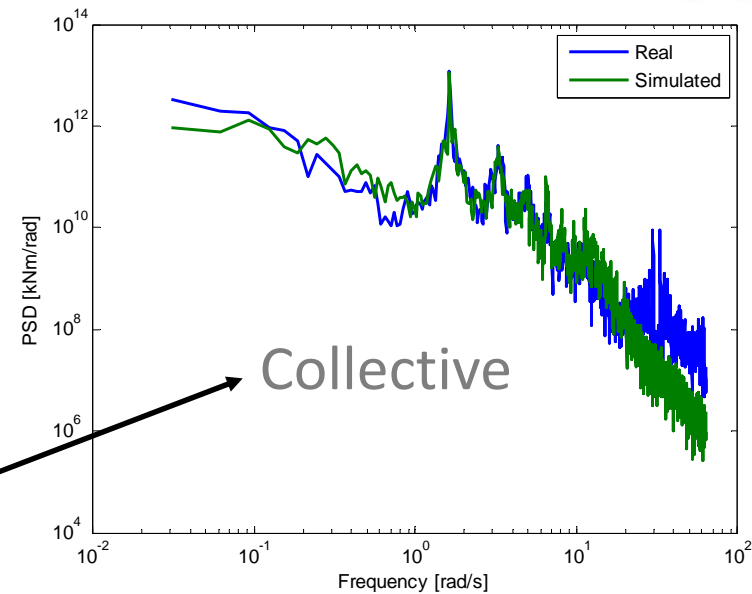


# Model Validation

Flapwise blade root load

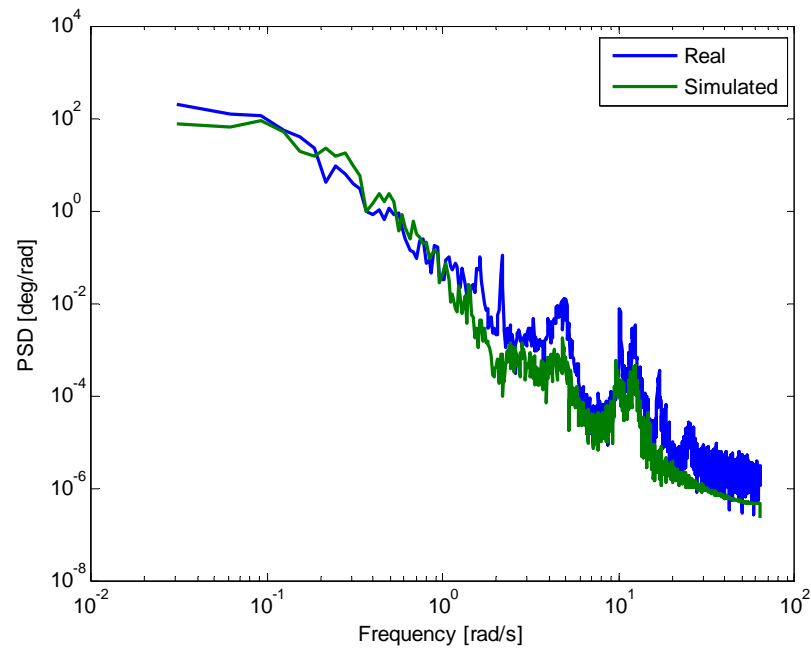


Blade loads reduction ~10 %

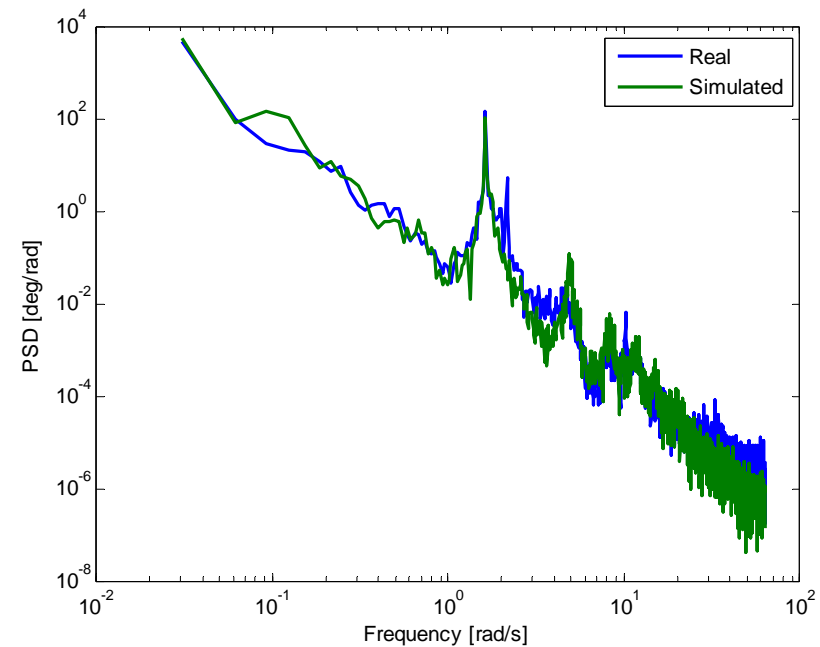


# Model Validation

 Pitch angle – real vs simulated



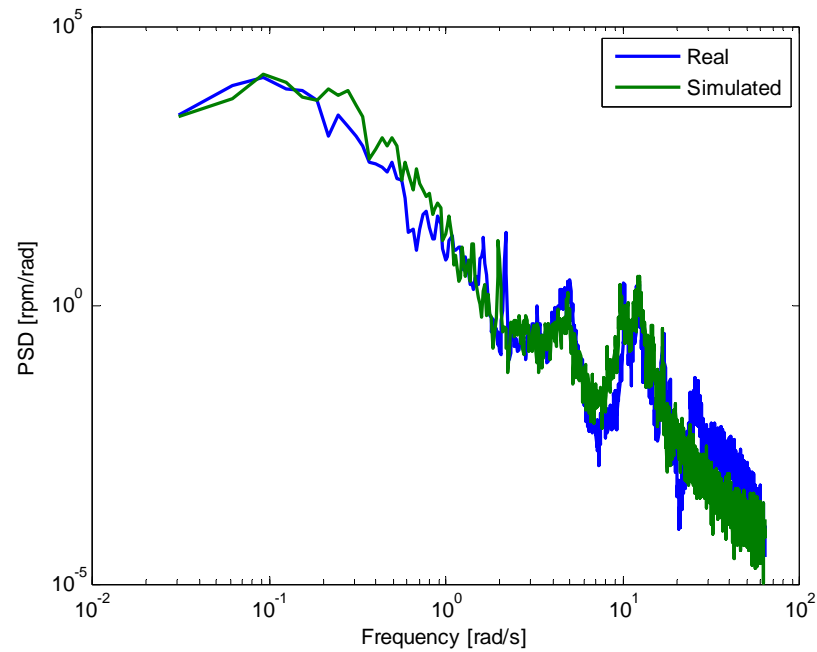
Collective



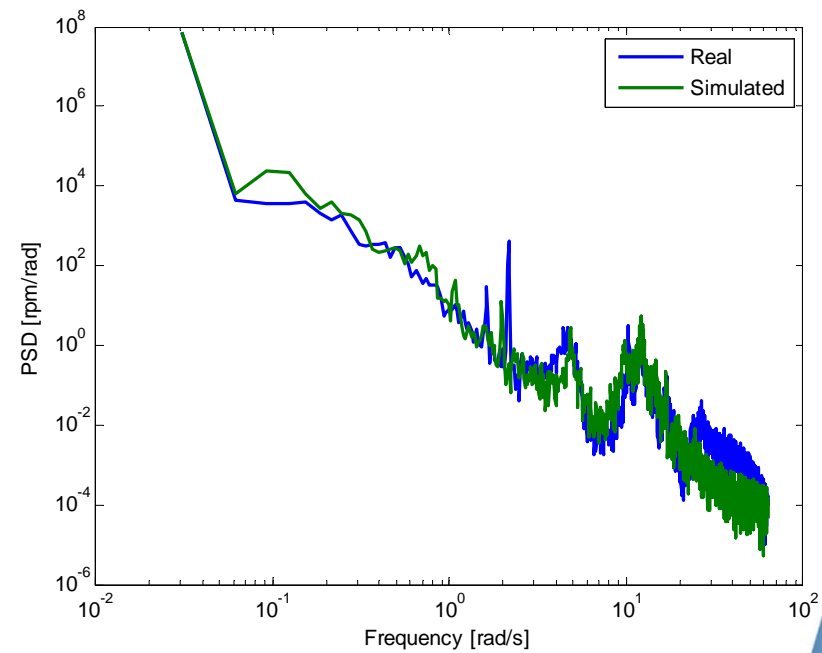
ATLAS

# Model validation

 Generator speed



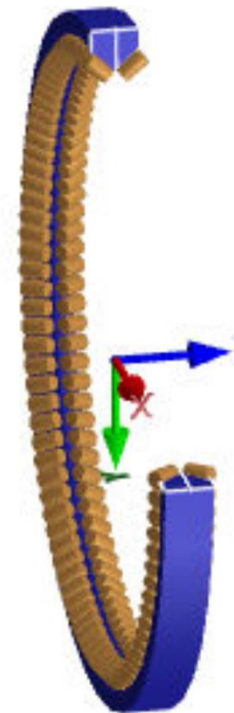
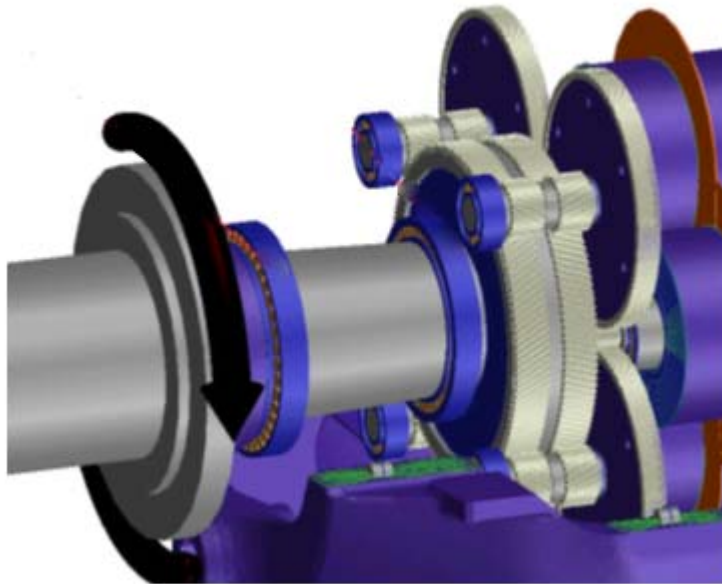
Collective



ATLAS

# Independent 3<sup>rd</sup> Party Analysis

- ~ Romax assessed lifetime of key components
- ~ *RomaxWIND* - Detailed models of gearbox and bearings
- ~ Standard and bespoke calculation methods



*RomaxWIND* models


# ATLAS – Main Benefits

 Blade fatigue loads reduction (10-25 %)

 Alleviate gearbox loads

 Less risk of main bearing failures

 CAPEX and OPEX reduction

 Minimum pitch activity -> does not impact the pitch bearing life

# End of the Story?



Endpoints of diameter:  $(3,5)$  and  $(-1,-4)$ .

$$\left(\frac{x_1+x_2}{2}, \frac{y_1+y_2}{2}\right) \quad d = \sqrt{(x_2-x_1)^2 + (y_2-y_1)^2}$$
$$\left(\frac{3+(-1)}{2}, \frac{5+(-4)}{2}\right) \quad d = \sqrt{(3-(-1))^2 + (5-(-4))^2}$$
$$\left(1, \frac{1}{2}\right) \quad = \sqrt{4^2 + 9^2}$$
$$(h, k) \quad d = \sqrt{16+81}$$
$$\quad \quad \quad d = \sqrt{97} \Rightarrow r = \frac{\sqrt{97}}{2}$$
$$(x-h)^2 + (y-k)^2 = r^2$$
$$(x-1)^2 + \left(y-\frac{1}{2}\right)^2 = \left(\frac{\sqrt{97}}{2}\right)^2$$
$$\therefore (x-1)^2 + \left(y-\frac{1}{2}\right)^2 = \frac{97}{4}$$



Idea

Development

Implementation

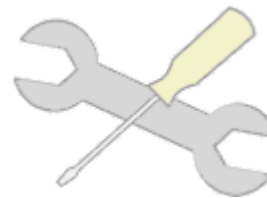
Demonstration

# Next Steps



Endpoints of diameter  $(3, 5)$  and  $(-1, -7)$

$$\left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2} \right) \quad d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$
$$\left( \frac{3 + (-1)}{2}, \frac{5 + (-7)}{2} \right) \quad d = \sqrt{(3 - (-1))^2 + (5 - (-7))^2}$$
$$\left( 1, -1 \right) \quad d = \sqrt{4^2 + 12^2}$$
$$\quad \quad \quad d = \sqrt{16 + 144} \Rightarrow d = \frac{\sqrt{160}}{2}$$
$$(x - h)^2 + (y - k)^2 = r^2$$
$$(x - 1)^2 + \left( y - \left( -1 \right) \right)^2 = \left( \frac{\sqrt{160}}{2} \right)^2$$
$$(x - 1)^2 + \left( y + 1 \right)^2 = \frac{40}{1}$$



Idea

Development

Implementation






Demonstration

Commercialisation





# Commercialisation

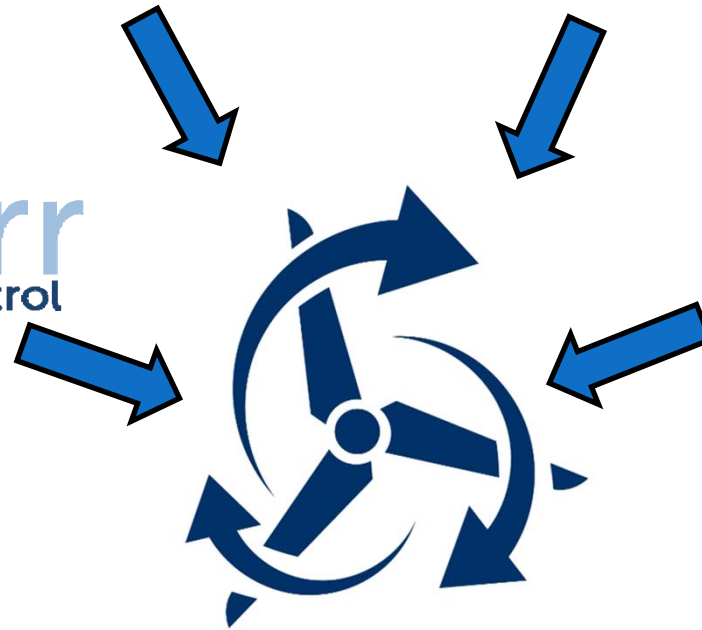
-  Moving to TRL Levels 8-9
-  Commercialisation and market ready
-  Using experience from field demonstration to finalise product design, packaging, marketing
-  Rollout to multiple sites and different wind turbine types
-  Future development of product improvements to increase capability and performance

# Target Markets

- ⌋ Wind turbine manufacturers
  - ⌋ Cost reduction of original design
  - ⌋ Increased energy capture with longer blades
  - ⌋ Essential for large wind turbines
  - ⌋ Life extension
  
- ⌋ Wind farm owners and operators
  - ⌋ High wind shear, veer, turbulence
  - ⌋ Low level jets
  - ⌋ High failure rates of components
  - ⌋ Life extension



Department  
of Energy &  
Climate Change



ATLAS™

